

23/11/2021

Lecture - 16

PRIMAL

✓ $[B] \rightarrow$ optimal part
✓ $B = [A_{B(1)} \dots A_{B(m)}]$

DUAL

$$\vec{u}^* = (B^{-1})^T C_B$$

dual optimal

✓ (1) find a lower bound for LPP.

✓ (2) verification certificate for alleged optimal solⁿ.

✓ (3) solve LPP ~~with~~ faster. $x_1, \dots, x_n$

$m \gg n$
look at the dual LPP.

$A_{m \times n}$

$a_{11}x_1, \dots, -a_{1n}x_n \leq b_1$
 $\vdots$
 $a_{m1}x_1, \dots, -a_{mn}x_n \leq b_m$

$m < n$

How to verify $\vec{v}^*$ is in fact an optimal solution to LPP?

COMPLEMENTARY SLACKNES

Theorem: Let P be a linear program in general form.

P :

$$mx \leq \vec{c}, x$$

$$s.t. - \quad \sum (A)^i \vec{x} = b_i, 1 \leq i \leq h$$

$$\sum (A)^i \vec{x} \leq b_i, h+1 \leq i \leq m$$

$$\sum x_j \geq 0, 1 \leq j \leq l$$

$$x_j \leq 0, l+1 \leq j \leq n$$

D:

$$\max \langle \vec{b}, \vec{y} \rangle$$

$$= y_i \geq 0, \quad 1 \leq i \leq h$$

$$= y_i \geq 0, \quad h+1 \leq i \leq m$$

$$A_j^T \vec{y} \leq c_j, \quad 1 \leq j \leq l$$

$$A_j^T \vec{y} = c_j, \quad l+1 \leq j \leq n.$$

Let $\vec{w}$ be PRIMAL feasible. and $\vec{u} \in \mathbb{R}^m$ be
DUAL feasible. Then $\vec{w}$ is primal optimal
and $\vec{u}$ is DUAL optimal if and only if

$$\underline{\underline{\left(\left(\sum_{j=1}^n a_{ij} w_j \right) - b_i \right) u_i = 0}} \quad \text{for } i=1, \dots, m$$

$$\left[(A^i \vec{w} - b_i) u_i = 0 \right]$$

$$\underline{\underline{\text{and } \left(\left(\sum_{i=1}^m a_{ij} u_i \right) - c_j \right) w_j = 0}} \quad \text{for } j=1, \dots, n.$$

$$\left[w_j (c_j - A_j^T \vec{u}) = 0 \right].$$

(If a dual variable is non-zero, then the corresponding primal constraint must be tight. If a primal variable is non-zero, then the corresponding dual constraint must be tight.)

Proof -

$$(\star) ((A)^i \vec{w} - b_i) u_i \geq 0, i=1, \dots, m$$

$$w_j (c_j - A_j^T \vec{u}) \geq 0, j=1, \dots, n$$

$$t := \sum_{i=1}^m \boxed{((A)^i \vec{w} - \boxed{b_i}) u_i} + \sum_{j=1}^n \boxed{w_j (c_j - A_j^T \vec{u})}$$

$$= - \sum_{i=1}^m b_i u_i + \sum_{j=1}^n w_j c_j$$

$$+ \boxed{\sum_{i=1}^m u_i (A)^i \vec{w}} \leftarrow \begin{matrix} \swarrow \\ \searrow \end{matrix} \begin{matrix} \vec{u}^T (A \vec{w}) \\ (A^T \vec{u})^T \vec{w} \end{matrix}$$

$$\sum_{j=1}^n w_j (A_j^T \vec{u}) \leftarrow \begin{matrix} \swarrow \\ \searrow \end{matrix} \begin{matrix} \vec{w}^T, A^T \vec{u} \end{matrix}$$

$$[t: \langle \vec{c}, \vec{w} \rangle - \langle \vec{b}, \vec{u} \rangle]$$

~~Let~~ $\vec{w}$ is primal optimal and $\vec{u}$ is dual optimal $\Rightarrow t=0$ by strong duality.

$$\Rightarrow \boxed{(A^T \vec{w} - \vec{b})} \quad u_i = 0, \quad i=1, \dots, m$$

$$\checkmark w_j (c_j - A_j^T \vec{u}) = 0, \quad j=1, \dots, n$$

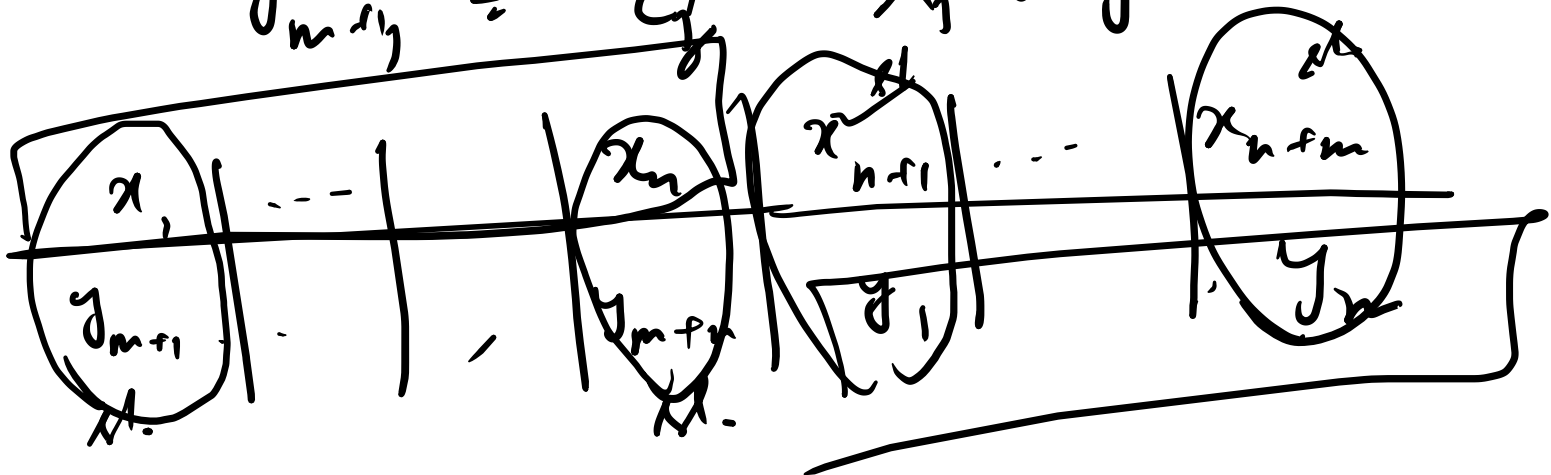
Q

What is complementary slackness?

The two conditions in the previous theorem look simple with slack variables.

$$x_{n+i} = (A)^i \vec{x} - b_i, \quad i=1, \dots, m$$

$$y_{m+j} = c_j - A_j^T \vec{y}, \quad j=1, \dots, n.$$



The two conditions imply that amongst the $m+n$ matching pairs, at least one variable must be zero

Theorem. (Certificate for optimality)

A feasible soln $\vec{w}$ of $[LP]$ is optimal

if and only if there are numbers $u_1, \dots, u_m$

such that

✓ (1) $\sum_{i=1}^m a_{ij} u_i \leq c_j$

whenever $w_j > 0$

✓ (2)

$u_i = 0$

whenever

(3)

$\vec{u}$

is

feasible

for

dual

of $[LP]$

$\sum_{j=1}^n a_{ij} w_j > b_i$

Proof - If $\vec{w}$ is optimal, then DUAL has
an optimal soln $\vec{u}$. This $\vec{u} = \begin{bmatrix} u_1 \\ \vdots \\ u_m \end{bmatrix}$
 $u_1, \dots, u_m$ - the entries of $\vec{u}$ satisfy
the given conditions

If $u_1, \dots, u_m$ satisfy (1), (2), (3), then by
complementary slackness, $\vec{w}$ is primal optimal.



Corollary. If $\vec{w}$ is a nongenerate bfs, then the system of equations (1), (2) has a unique solⁿ.

Prat. $\sum_{i=1}^m a_{ij} u_i = c_j$, where $u_j > 0$.

$\vec{w}$ ~~is~~ is a bfs corresponding $B = [\underline{B(1)}, \dots, \underline{B(m)}]$

$$\sum_{i=1}^m a_{B(i)} u_i = C_{B(i)}$$

$$\begin{aligned} B &= [A_{b_1}, \dots, A_{b_m}] \\ B^T \vec{u} &= \vec{C_B} \\ \vec{u} &= (B^{-1})^T \vec{C_B} \end{aligned}$$

Example : Consider the following data:

$$\vec{x}^* =$$

$$\begin{pmatrix} 1 \\ -1 \\ 2 \\ 0 \\ -3 \end{pmatrix}$$

is an optimal solⁿ to
the LPP given below;

$$\min \quad \boxed{-4x_1 + 2x_2 - 11x_3 + 4x_4 + 0x_5}$$

$$\text{s.t.} \quad \begin{cases} 2x_1 - x_2 + 3x_3 - 2x_4 + x_5 = 6 \\ x_1 + 4x_2 - x_3 - x_4 - 3x_5 \geq 4 \end{cases} \quad (\text{right at } \vec{x}^*)$$

$$\begin{cases} x_1 \geq 0 \\ x_2 \geq 0 \\ x_3, x_4 \geq 0 \\ x_5 \leq 0 \end{cases}$$

$$\begin{cases} x_1 + 4x_2 - x_3 - x_4 - 3x_5 \geq 4 \\ 4x_1 + 6x_2 - x_3 - 5x_4 + x_5 \geq -8 \end{cases} \quad \begin{matrix} (\text{right at } \vec{x}^*) \\ (\text{not right at } \vec{x}^*) \end{matrix}$$

DUAL $\max$ $6y_1 + 4y_2 - 8y_3$

st. $\boxed{2y_1 + y_2 + 4y_3 \leq -4}$

$\boxed{-y_1 + 4y_2 + 6y_3 = 2}$

$\boxed{3y_1 - y_2 - y_3 \leq -11}$

$y_1 \geq 0$

$y_2 \geq 0$

$y_3 \geq 0$

$-2y_1 - y_2 - 5y_3 \leq 4$

$y_1 - 3y_2 + y_3 = 0$

$\begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}$

if $\bar{x}^*$ is primal optimal, CST asserts that

if $\bar{y}^*$ is dual optimal,

$$2y_1^* + y_2^* + 4y_3^* = -4 \quad (\text{since } x_1^* > 0)$$

$$3y_1^* - y_2^* - y_3^* = -11 \quad (\text{since } x_3^* > 0)$$

$$y_3^* = 0$$

~~$y_1^* =$~~

$$\left[\begin{array}{cc|c} 2 & 1 & 4 \\ 3 & -1 & -1 \\ \hline 0 & 0 & 1 \end{array} \right] \begin{bmatrix} y_1^* \\ y_2^* \\ y_3^* \end{bmatrix} = \begin{bmatrix} -4 \\ -11 \\ 0 \end{bmatrix}$$

$$\vec{y} = \begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}$$

$\Rightarrow \begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}$ must be dual optimal.

But, $\begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}$ is not even dual feasible.

Hence, $\vec{y}$ is not primal optimal.

APPLICATIONS OF DUALITY

Theorems of the Alternatives

Farkas Lemma (I): Exactly one of the following alternatives holds.

(1) $A\vec{x} \leq \vec{b}$ has a solⁿ, $\vec{x} \in \mathbb{R}^n$

(2) There is a vector $\vec{y} \in \mathbb{R}^m$ such that
 $\vec{y} \geq \vec{0}$, $A^T \vec{y} = \vec{0}$, $\langle \vec{b}, \vec{y} \rangle < 0$.

Proof: PRIMAL

max $\langle \vec{b}, \vec{x} \rangle$
s.t. $A\vec{x} \leq \vec{b}$, $\vec{x} \geq \vec{0}$

DUAL -

min

$$\langle \vec{b}, \vec{y} \rangle$$

$$A^T \vec{y} = \vec{0} \quad (\text{E.25})$$

$$\vec{y} \geq \vec{0}$$

(1) $\Rightarrow$ (2)^c

If PRIMAL is feasible and hence has 0 as its optimal cost. By strong duality, DUAL has optimal cost 0, and hence $\langle \vec{b}, \vec{y} \rangle \geq 0$, whenever $A^T \vec{y} = \vec{0}$ and $\vec{y} \geq \vec{0}$.

$$(2)^c \Rightarrow (1)$$

DUAL is clearly not unbounded.

$$\langle \vec{b}, \vec{z} \rangle \geq 0$$

Thus DUAL is feasible and bounded.

$\Rightarrow$ PRIMAL is feasible and bounded.

$\Rightarrow A\vec{x} \leq \vec{b}$ is feasible.

Farkas' Lemma (2): Exactly one of the two alternatives hold.

$\Rightarrow$ (1) $\left[A \vec{x} = \vec{b}, \vec{x} \geq \vec{0} \right]$ has a solⁿ;

(2) $\left| \begin{array}{l} \exists \vec{y} \in \mathbb{R}^n \text{ s.t. } A^T \vec{y} \leq \vec{0} \text{ and} \\ \langle \vec{b}, \vec{y} \rangle > 0 \end{array} \right|$ (circled $\vec{y}$) $\rightarrow$ certificate of infeasibility)

Proof, left is an exercise.

Geometric interpretation of Farkas' lemma 2:

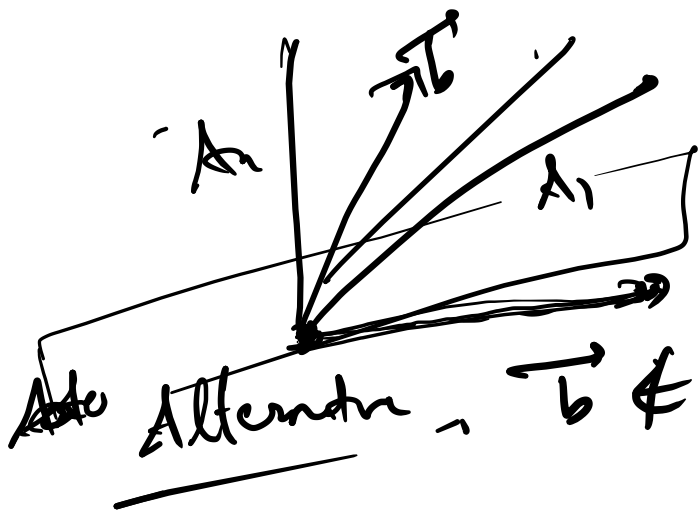
$$A\vec{x} = \vec{b}, \vec{x} \geq 0$$

$$\vec{b} = x_1 \underbrace{A_1}_{1^{\text{st}} \text{ column of } A} + \dots + x_n \underbrace{A_n}_{n^{\text{th}} \text{ column of } A}$$

$$x_1 \geq 0, \dots, x_n \geq 0$$

$$A\vec{x} = \vec{b}, \vec{x} \geq 0 \text{ is feasible}$$

$$\Leftrightarrow \vec{b} \in \text{convex cone generated by } A_1, \dots, A_n$$



convex cone generated by $A_1, \dots, A_n$.

$\Leftrightarrow \exists$ a hyperplane passing through the origin that ^{strictly} separates $\vec{b}$ and the column ~~vectors~~ of A . Let $\vec{y}$ be normal to the hyperplane.

$$\boxed{\langle \vec{y}, A_i \rangle \leq b_i, \quad i=1, \dots, n}$$

$$\langle \vec{y}, \vec{b} \rangle > 0$$

$$\boxed{A^T \vec{y} \leq \vec{c}}$$

$$\langle \vec{b}, \vec{y} \rangle > 0$$

WEAK DUALITY

PRIMAL

$$\min \langle \vec{c}, \vec{x} \rangle$$

$$A\vec{x} = \vec{b}$$

$$\vec{x} \geq 0, \quad x^u$$

DUAL

to show,

$$\max \langle \vec{b}, \vec{y} \rangle$$

s.t.

$$A^T \vec{y} \leq \vec{c}$$

$$\vec{y} \leq \vec{0}$$

P.

Pf. x is feasible, $Ax = b$

y is feasible in DUAL, $A^T y \leq c$

$$\langle y, b \rangle = \langle y, Ax \rangle = \langle A^T y, x \rangle \\ \leq \langle c, x \rangle$$

$\therefore \langle y, b \rangle \leq \alpha^*$, $\forall y \in \text{DUAL feasible}$

$$\therefore b^* \leq \alpha^*$$

STRONG DUALITY revisited:

If either PRIMAL or DUAL is feasible,
then $\alpha^* = \beta^*$.

Proof. Why, PRIMAL is feasible.
If PRIMAL is unbounded, $\alpha^* = -\infty = \beta^*$
(by weak duality), we are done.

Let $\vec{x}^*$ be an optimal solⁿ for PRIMAL.

Let $\langle \vec{c}, \vec{x}^* \rangle = \alpha^*$.
There are ~~no~~ NO vectors $\vec{x} \in \mathbb{R}^n$ such that
 $A\vec{x} = \vec{b}$, $\vec{x} \geq \vec{0}$, and $\langle \vec{c}, \vec{x} \rangle = \alpha^* - \epsilon$
($\epsilon > 0$.)

$$\begin{bmatrix} A \\ -\vec{c}^T \end{bmatrix} \vec{x} = \begin{bmatrix} \vec{b} \\ -\alpha^* \epsilon \end{bmatrix}$$

$$\vec{x} \geq 0 \quad \text{is infeasible.}$$

By Farkas lemma, $\exists (\vec{u}, z) \in \mathbb{R}^{m+1}$

such that

$$\begin{bmatrix} A \\ -\vec{c}^T \end{bmatrix}^T \begin{bmatrix} \vec{u} \\ z \end{bmatrix} \leq 0, \quad \begin{bmatrix} \vec{b} \\ -\alpha^* \epsilon \end{bmatrix}^T \begin{bmatrix} \vec{u} \\ z \end{bmatrix} > 0.$$

$$\iff \{ A^T \vec{u} \leq z \vec{c}^* \}$$

$$\vec{u} \in \mathbb{R}^m, z \in \mathbb{R}.$$

$$\langle \vec{b}, \vec{u} \rangle > z (\alpha^* \epsilon)$$

Claim: We ~~must have~~ $\langle \vec{b}, \vec{u} \rangle \leq z\alpha^*$.

Proof: (If not, then), $\langle \vec{b}, \vec{u} \rangle > z\alpha^*$, $\begin{bmatrix} \vec{b} \\ -\alpha^* \end{bmatrix}^T$

$$\begin{pmatrix} A \\ -\vec{c}^T \end{pmatrix}^T \begin{pmatrix} \vec{x} \\ z \end{pmatrix} \leq 0, \quad \begin{pmatrix} \vec{b} \\ -\alpha^* \end{pmatrix}^T \begin{pmatrix} \vec{u} \\ z \end{pmatrix} > 0.$$

then, $\begin{pmatrix} A \\ -\vec{c}^T \end{pmatrix}^T \vec{x} = \begin{pmatrix} \vec{b} \\ -\alpha^* \end{pmatrix}$

$$\vec{x} \geq 0$$

Contradiction!:-

is not feasible

$$A\vec{x} = \vec{b}, \quad \langle \vec{c}, \vec{x} \rangle = \alpha^*$$

$$\vec{x} \geq 0$$

$$\boxed{A^T u \in \mathbb{Z}^T}$$

$$\mathbb{Z}(\alpha^{\alpha-1}) \langle \tau, u \rangle \leq \mathbb{Z} \alpha^{\alpha}.$$

$$\Rightarrow \text{~~some scribbles~~} - \mathbb{Z} \leq 0$$

$$\mathbb{Z} \text{ ~~scribbles~~ } \mathbb{Z} > 0$$

$$\mathbb{Z} \boxed{\mathbb{Z} > 0}$$

We may assume $\mathbb{Z} \neq 1$, wlog.

For some $\bar{u} \in \mathbb{R}^n$,

$$A^T \bar{u} \leq \bar{c}$$

and $\alpha^* \leq \langle \bar{b}, \bar{u} \rangle$

In other words there is a DUAL feasible vector $\bar{u}$ s.t. $\alpha^* \leq \langle \bar{b}, \bar{u} \rangle \leq \beta^*$

$$\Rightarrow \alpha^* \leq \beta^*, \quad \forall \epsilon > 0$$

$$\Rightarrow \alpha^* \geq \beta^*$$

$$\Rightarrow \boxed{\alpha^* = \beta^*} \quad \square$$

Economic interpretation of primal is clear.

ECONOMIC INTERPRETATION OF THE DUAL

Dimension analysis,

$$A \vec{x} \leq \vec{b}$$

$$a_{11}x_1 + a_{1n}x_n \leq b_1$$

$$\vdots$$
$$a_{m1}x_1 + a_{mn}x_n \leq b_m$$

$x_j \rightarrow$ quantity of product P_j

$$\begin{matrix} \textcircled{T_2} & 2a_{12} & \textcircled{\frac{T_1}{2}} \\ \text{---} & & \text{---} \\ & f(L_1) & \end{matrix}$$

~~has~~ $b_i \rightarrow$ quantity of resource R_i

$a_{ij} \rightarrow$ unit of resource R_i per unit of product P_j .

$c_j \rightarrow$ profit per unit of product P_j .

units of $c_j \rightarrow$ rupees per unit of product P_j
units of $a_{ij} \rightarrow$ amount of resource R_i per unit of product P_j .

$A \rightarrow B$,

$$\begin{matrix} A^T y & \leq & c \\ \sum (a_{ij} y_j) & \leq & b_i \end{matrix}$$

unit of y_i $\rightarrow$ value per unit of resource b_i .
(dual variable)

Theorem - Consider

(PRIMAL)

(P)

s.t.

$$Ax = b$$

$$x \geq 0$$

min $\langle c, x \rangle$ (in LPS)

Suppose that P has at least one nondegenerate
basic optimal solⁿ, then there is a unique
 $\vec{u}^* \in \mathbb{R}^m$ which is ~~the~~ optimal in the
dual LP.

Furthermore, there is an $\varepsilon > 0$ with the following property..

Suppose $\vec{t} \in \mathbb{R}^n$ and $|\vec{t}| \leq \varepsilon$ then...

Then

(P')

$$\begin{aligned} \text{we } & \langle \vec{c}, \vec{x} \rangle \\ A\vec{x} &= \vec{b} + \vec{t} \\ \vec{x} &\geq \vec{0}. \end{aligned}$$



has an optimal solⁿ and its value is v
 $[c^* \in \langle \vec{c}, \vec{x} \rangle]$ where $\vec{c}^*$ is one optimal
 cost of P and $\vec{u}^*$ is dual optimal.

Proof. $B = B(1) \dots B(m)$ corresponding to
the optimal nondegenerate bfs $\vec{w}^*$.

$$\left(\begin{array}{c|c} \text{min} & \\ \hline B^{-1}b & B^{-1}A \end{array} \right)$$

$$B = [A_{B(1)} \ A_{B(m)}]$$

cost C^* of $\vec{w}^* =$

row 0 =

$$\begin{array}{c} \vec{C}_B^T B^{-1}b \\ \hline \vec{C}^T - \left(\vec{C}_B^T B^{-1}A \right) \end{array}$$

$B'^T \vec{t} > \vec{0}$, as $\vec{t}$ is nondegenerate.

$\boxed{\delta}$ → smallest component of $B'^T \vec{t}$.

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$x \rightarrow \textcircled{B^{-1}}_n \quad \text{is continuous}$$

$\exists \epsilon > 0$ s.t. when $\|\vec{t}\|_\infty \leq \epsilon$, we have

$$\boxed{\|B'^T \vec{t}\|_\infty \leq \delta.}$$

$$\checkmark \quad B^{-1} \textcircled{(\vec{t} + \vec{t})} : \textcircled{B'^T \vec{t}} \textcircled{B'^T \vec{t}} \geq \vec{0}.$$

B yields $\sim$ bps for P' .

Tableau corresponding to B for P' is
 the same everywhere (except column 0) as
 the tableau corresponding to B for P .

In particular, 0th row (except 0th entry)
 has no negative entries. Thus B is an optimal
 basis for P' .

$$\begin{array}{l}
 C' = \begin{array}{c} \overline{C_B'} \quad \overline{B'} \end{array} \quad (\overline{b} + \overline{f}) \quad \text{(optimal val for } P') \\
 \underbrace{\begin{array}{c} \overline{u}'' = \begin{array}{c} \overline{B'}^T \overline{C_B'} \end{array} \end{array}}_{= \overline{C_B}} \quad \underbrace{\overline{u}''^T (\overline{b} + \overline{f})}_{= \overline{C_B}^T (\overline{b} + \overline{f})}
 \end{array}$$

$$C^1: \langle \vec{u}^*, \vec{b}, t \rangle$$

$$= \langle \vec{u}^*, \vec{b} \rangle + \langle \vec{u}^*, t \rangle$$

$$= C^* + \langle \vec{u}^*, t \rangle$$

$$\vec{u}^*$$

... $u_1^*, u_2^*, \dots$

vector of dual

optimal variables

$u_i^* \rightarrow$ marginal value of the i^{th} resource
if the i^{th} resource is changed by ϵ units
small, the profit will increase by $\boxed{u_i^* \epsilon}$