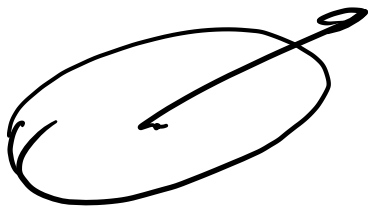


16/11/2021

Lecture - 14

Duality:

Earlier, we had seen two representation theorems for convex bodies



Duality translates results on boundary points of closed convex sets into results on support planes (or normal vectors) associated with a "dual" convex set.

Example : $\underbrace{(K_1)}_{\cap H_i^-}, \underbrace{(K_2)}_{\cap H_i^-}$

$$\underbrace{(K_1)}_{\cap H_i^-} \cap \underbrace{(K_2)}_{\cap H_i^-} = (\cap H_i^-) \cap (\cap H_i^-)$$

For intersection of convex sets the supporting hyperplane description easily carries forward.

$$\text{conv}(K_1 \cup K_2) = \text{conv}(\underbrace{x_1, \dots, x_k, x_{k+1}, \dots, x_n}_{\substack{\nearrow \\ K_1 = \text{conv}\{x_1, \dots, x_k\}, K_2 = \text{conv}\{x_{k+1}, \dots, x_n\}}})$$

Defn: Let K be a closed convex set in $\mathbb{R}^n$.
 The **polar body** (or **dual body**)^{of K} , denoted by K° , is defined as follows.

$$K^\circ = \{ \vec{y} \in \mathbb{R}^n \mid \underbrace{\langle \vec{x}, \vec{y} \rangle}_{\text{for every } \vec{x} \in K} \leq 1 \}$$

Properties of polar bodies

- (1) K° is non-empty (contains $\vec{0}$)
- (2) If K is closed, convex and contains $\vec{0}$, then

$$(K^*)^* = K$$

Pf.:

$$K \subset (K^*)^*$$

$$\vec{x} \in K$$

$$\vec{y} \in K^*$$

$$\vec{y} \in (K^*)^*$$

$$\langle \vec{x}, \vec{y} \rangle \leq 1$$

$$\forall \vec{x} \in K, \vec{y} \in K^*$$

$$\langle \vec{y}, \vec{x} \rangle \leq 1$$

$(K^*)^*$ is closed, convex

and $0 \in (K^*)^*$

closed: L^* is closed for any convex set L , in $\mathbb{R}^n$

$$\vec{y}_n \in L^* \text{ s.t. } \vec{y}_n \rightarrow \vec{y} \quad \langle \vec{x}, \vec{y}_n \rangle \leq 1 \quad \forall \vec{x} \in L$$

$$\Rightarrow \langle \vec{x}, \vec{y} \rangle \leq 1, \forall \vec{x} \in L$$

convex: $\vec{y}_1, \vec{y}_2 \in L$,

$$\langle \vec{x}, \vec{y}_1 \rangle \leq 1 \quad \forall \vec{x} \in L.$$

$$\langle \vec{x}, \vec{y}_2 \rangle \leq 1$$

$$\langle \vec{x}, \lambda \vec{y}_1 + (1-\lambda) \vec{y}_2 \rangle \leq 1, \quad \forall \vec{x} \in L$$

$\lambda \in [0, 1]$

Let $\vec{z} \in \mathbb{R}^n \setminus K$

There is a hyperplane $H_{\vec{a}, b}$ .

($\vec{a} \neq \vec{0}$, $b \in \mathbb{R}$)

with $K \subset H_{\vec{a}, b}$ and $\langle \vec{a}, \vec{x} \rangle \leq b$

$\langle \vec{z}, \vec{a} \rangle > b$
here, $b > 0$ since $\vec{0} \in K$.

(using strong separation theorem for a closed convex set in $\mathbb{R}^n$ and a point outside of it)

For all $\bar{y} \in K$, we have $\langle \bar{y}, \bar{a}/b \rangle \leq 1$

so that $\frac{1}{b} \bar{a} \in K^*$

$$\langle \bar{z}, \bar{a}/b \rangle > 1 \Rightarrow \bar{z} \notin L^* \subseteq (K^*)^*$$

We have shown that $(K^*)^* \subseteq K$

(3) Polarity reverses containment: $\boxed{K \subseteq L}$ (closed, convex sets in $\mathbb{R}^n$)
 $\Rightarrow L^* \subseteq K^*$

(4) K_1, K_2 closed, convex sets in $\mathbb{R}^n$.

$$(K_1 \cap K_2)^* = \text{conv}(K_1^* \cup K_2^*)$$

Proof: $K_1 \cap K_2 \subset K_i, i=1, 2$

$$\Rightarrow K_i^* \subset (K_1 \cap K_2)^*$$

$$\Rightarrow \text{conv}(K_1^* \cup K_2^*) \subset (K_1 \cap K_2)^*$$

$$K_i \subset \text{conv}(K_1 \cup K_2), i=1, 2$$

$$\Rightarrow (\text{conv}(K_1 \cup K_2))^* \subset K_i^*, i=1, 2$$

$$\Rightarrow (\text{conv}(K_1 \cup K_2))^* \subset K_1^* \cap K_2^*$$

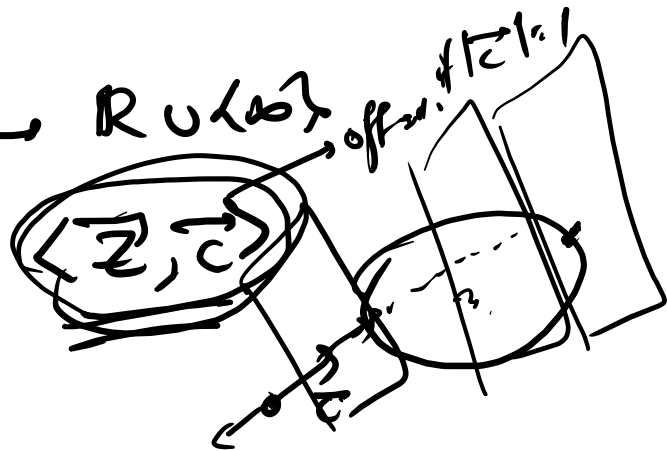
$$\Rightarrow (K_1^* \cap K_2^*)^* \subset \text{conv}(K_1 \cup K_2)$$

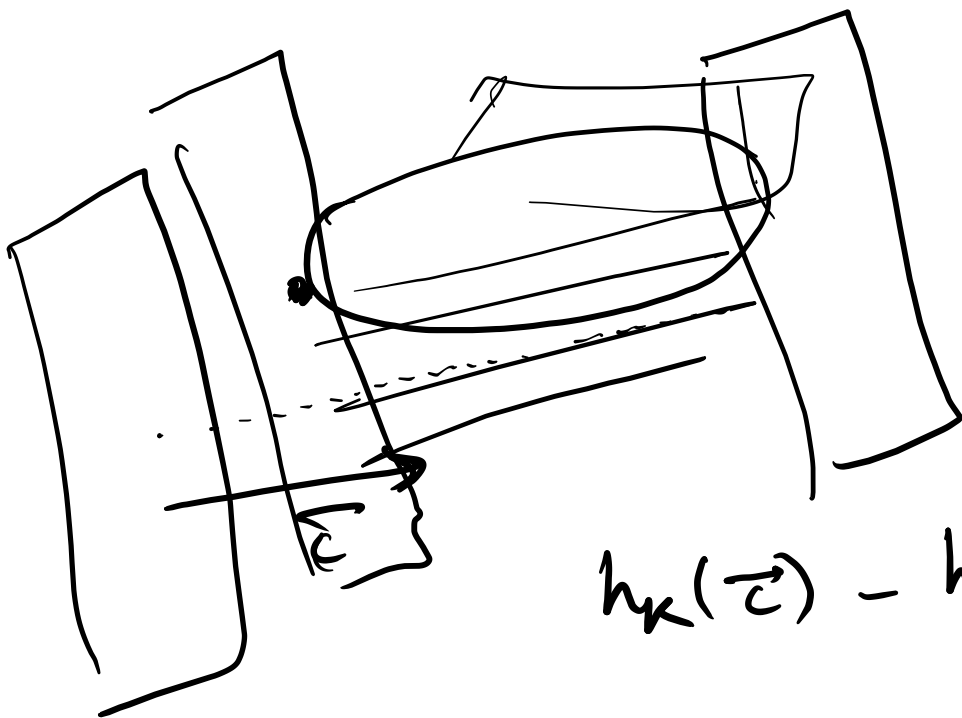
$$\Rightarrow (K_1 \cap K_2)^* \subset \text{conv}(K_1^* \cup K_2^*)$$

Defn. support function of K .

$$h_K : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R} \cup \{\infty\}, \text{ off. } \|\vec{c}\| = 1$$

$$\underline{h_K(\vec{c})} = \sup_{\vec{z} \in K}$$



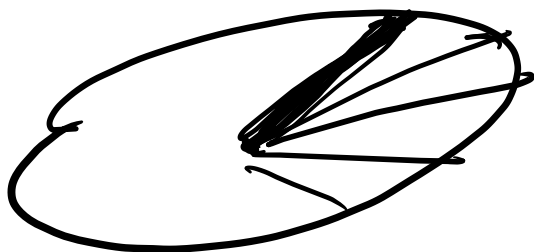


$$h_K(\vec{z}) - h_K(-\vec{z})$$

for $\vec{z}$ a unit vector

= width of K along the direction
of $\vec{z}$.

Radial function of K (containing $\vec{0}$)



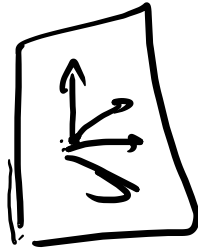
$$f_K(\vec{b}) = \sup \{ \lambda \geq 0 : \underline{\underline{\lambda \vec{b}}} \in K \}$$



Lemma. Let $K \subseteq \mathbb{R}^n$ closed, convex and containing $\vec{0}$. For every non-zero vector $\vec{u} \in \mathbb{R}^n$,

$$\underline{h_K}(\vec{u}) = \frac{1}{\rho_{K^*}(\vec{u})} \quad \text{and} \quad h_{K^*}(\vec{u}) = \frac{1}{\rho_K(\vec{u})}$$

with the convention, $\frac{1}{\infty} = 0$, and $\frac{1}{0} = \infty$.



Proof -

$$p_{K^*}(\bar{u}) = \sup_{\lambda \geq 0} \langle \lambda, \lambda \bar{u} \in K^* \rangle$$

$$\langle \lambda \bar{u}, \bar{x} \rangle \leq 1, \forall \bar{x} \in K$$

$$\Rightarrow \frac{\langle \bar{x}, \bar{u} \rangle}{h_K(\bar{u})} \leq \frac{1}{\lambda}, \forall \bar{x} \in K$$

$$\text{If } p_{K^*}(\bar{u}) = 0$$

$$\varepsilon \bar{u} \in K^*, \forall \varepsilon > 0$$

$$\exists \text{ some } \bar{x}_\varepsilon \in K \text{ s.t. } \langle \varepsilon \bar{u}, \bar{x}_\varepsilon \rangle > 1.$$

$$\langle \bar{u}, \bar{x}_\varepsilon \rangle > \frac{1}{\varepsilon}$$

$$h_K(\bar{u}) > \frac{1}{\varepsilon}$$

In geometric terms, LP asks for finding value of support function of specific convex bodies (polyhedra) in a particular direction (determined by the cost vector).

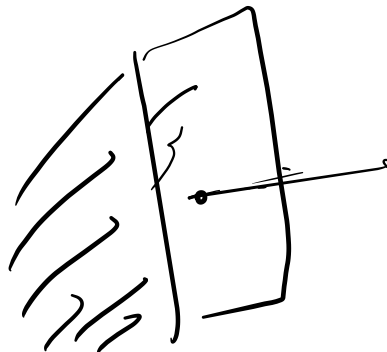
Computing the polar body of a polyhedron

$\vec{0} \in H_{\vec{a}, b}$
so that
 $b > 0$

$$(H_{\vec{a}, b}^-)^*$$

$$\{ \langle \vec{a}, \vec{\lambda} \rangle \leq b \}$$

$$b > 0, b \neq 0$$



Case 1... $b > 0$

$$(H_{\vec{a}, b}^-)^*$$

$$[0, \frac{1}{b} \vec{a}]$$

$$(H_{\vec{a}, 0}^-)^*$$

$$= \{ \underline{\lambda \vec{a}} : \lambda \geq 0 \}$$

$$\left(\left[0, \frac{1}{b} \vec{a} \right] \right)^* \text{ where } \boxed{b > 0}$$

$$\left\{ \vec{x} \in \mathbb{R}^n : \langle \vec{x}, \lambda \vec{a} \rangle \leq 1 \right. \\ \left. \text{for } \underline{0 \leq \lambda \leq \frac{1}{b}} \right\}$$

$$= \{ \vec{x} \in \mathbb{R}^n : \langle \vec{x}, \vec{a} \rangle \leq b \}$$

$$= H_{\vec{a}, b}^-$$

$$\underline{\text{Case II}} : b = 0$$

$$([0, \infty) \vec{a})^*$$

$$= \{ \vec{x} \in \mathbb{R}^n : \langle \vec{x}, \vec{a} \rangle \leq 1 \\ \forall 0 \leq \lambda \}$$

$$= \{ \vec{x} \in \mathbb{R}^n : \langle \vec{x}, \vec{a} \rangle \leq 0 \}$$

$$= H_{\vec{a}, 0}$$

Proposition: Let K be a convex polyhedron in $\mathbb{R}^n$ containing $\vec{0}$ (not necessarily in the interior). Let $K = \{A\vec{x} \leq \vec{b}\}$

$\swarrow$ $\searrow$
 $\mathbb{R}^n$ $\mathbb{R}^n$ $\mathbb{R}^n$
 $\downarrow$
 $m \times n$ matrix
 $\downarrow$
 i th row vector of A .

$\nabla \langle \vec{a}_i, \vec{x} \rangle \leq b_i$

Then,

$$K = \left\{ \sum_{i=1}^m \mu_i \vec{a}_i : \mu_i \geq 0 \text{ for all } i \right\}$$

$\checkmark$

and $\sum_{i=1}^m \mu_i \vec{b}_i \leq \vec{0}$

Proof: $\boxed{(K_1 \cap \dots \cap K_m)^{\circ} = \text{conv}(K_1^{\circ} \cup K_2^{\circ} \cup \dots \cup K_m^{\circ})}$

$K_i = H(\vec{a}_i, b_i) \quad K_i^{\circ} = \left[\vec{0}, \frac{1}{b_i} \vec{a}_i \right]$

$K^{\circ} = \text{conv}\left(\vec{0}, \frac{1}{b_1} \vec{a}_1, \dots, \frac{1}{b_m} \vec{a}_m\right)$

$\rightarrow \underbrace{\left(\frac{\lambda_1}{b_1} \vec{a}_1\right)}_{\mu_1} + \dots + \underbrace{\left(\frac{\lambda_m}{b_m} \vec{a}_m\right)}_{\mu_m} + \lambda_{m+1} \vec{0}$

$\boxed{\lambda_1 + \dots + \lambda_{m+1} = 1}$

$\lambda_1 + \dots + \lambda_m \leq 1$ λ_i, b_i fixed

Consider an LPP $(\min(\vec{c}, \vec{x}) \text{ s.t. } A\vec{x} \leq \vec{b})$ such that

$\vec{b} \in \Phi$ (so that $\vec{b} \geq \vec{0}$)

$$v_{\min} = \boxed{h_K(-\vec{c})} \quad (\text{optimal value})$$

$$\frac{1}{v_{\min}} = \frac{1}{\boxed{h_K(-\vec{c})}} = \boxed{p_{K^*}(-\vec{c})} = \sup_{p \geq 0} \{ p \mid -p\vec{c} \in K^* \}$$

The polar set of E is (K^*)

$$K^* = \left\{ \sum_{i=1}^n z_i \vec{a}_i : \vec{z}_i \geq 0, \langle \vec{b}, \vec{z} \rangle \leq 1 \right\}$$

We want the largest non-negative number p st.

$$\boxed{-p\vec{c} = \sum_{i=1}^n z_i \vec{a}_i, \vec{z}_i \geq 0, \langle \vec{b}, \vec{z} \rangle \leq 1}$$

(If LPD is bounded) we may pick $p > 0$
st. $-p\vec{c} \in K^*$. Define, $y_i = -\frac{z_i}{p} \leq 0$.

$$\boxed{\vec{c} = \sum_{i=1}^n y_i \vec{a}_i, \vec{y}_i \leq 0}$$

$$\langle \vec{b}, \vec{y} \rangle \geq -\frac{1}{p}$$

$$\left(\begin{array}{l} \vec{b} \geq \vec{0}, \vec{y} \leq \vec{0} \\ \Rightarrow \langle \vec{b}, \vec{y} \rangle \leq 0 \end{array} \right)$$

$$\boxed{-\frac{1}{p} \leq \langle \vec{b}, \vec{y} \rangle \leq 0}$$

Maximizing p is equivalent to maximizing $\langle \vec{b}, \vec{y} \rangle$.

Maximize
subject to

$$(b', \bar{y})$$

$$A^T \bar{y} = \bar{c}, \quad \bar{y} \leq \bar{u}$$

The computational viewpoint

Example: min. $x_1 + 2x_2 - 7x_3$

$$\text{s.t. } -3x_1 - x_2 + 5x_3 = 6$$

$$2x_1 + 0x_2 - x_3 = 12$$

$$x_1 \geq 0, x_2 \geq 0, x_3 \geq 0.$$

$$\begin{pmatrix} 1 \\ 2 \\ -7 \end{pmatrix}$$

$\mathbb{R}$

$$\vec{w} \in \mathbb{R}^3, \quad \vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \in \mathbb{R}^2.$$

$$f = y_1 (3w_1 - w_2 + 5w_3) + y_2 (2w_1 - w_2)$$

$$= \boxed{6y_1 + 12y_2} \text{ has no dependence on } \vec{w}$$

$$\begin{aligned} &= \frac{(3y_1 + 2y_2)w_1 + (-y_1)w_2}{+ (5y_1 - y_2)w_3} \end{aligned}$$

$$\leq w_1 + 2w_2 - 7w_3$$

$\in \langle \vec{c}, \vec{w} \rangle$

If the coefficients of w_1, w_2 satisfied

$$\begin{cases} 3y_1 + 2y_2 \leq 1 \\ -y_1 \leq 2 \\ 5y_1 - y_2 \leq -7 \end{cases} \quad - \text{ } F'$$

(No sign-conditions on y_1, y_2)

then, f is a lower bound for $\langle C, x \rangle$.

Maximizing $f = 6y_1 + 12y_2$ or F' would lead to an even better lower bound for LPP.

W Remark on why talk about these lower bounds when simplex method already gives optimal solⁿ (greatest lower bound) ?

sanity check / verification of obtained solution.

Example : min. $3x_1 - x_2 - 4x_3$

sub-pro.
$$\begin{cases} 5x_1 - 6x_2 + 7x_3 \leq 9 \\ 6x_1 - 9x_2 - 2x_3 \geq -7 \\ x_1 \geq 0, x_2 \geq 0, x_3 \geq 0. \end{cases}$$

Let $w \in F$, $y \geq 0$.

$$f \leq y_1 (5w_1 - 6w_2 + 7w_3) + y_2 (6w_1 - 9w_2 - 2w_3)$$

$y_1 \geq 0$, $y_2 \geq 0$

$$f \geq 9y_1 - 7y_2$$

$$\begin{aligned} f &= \underline{(5y_1 + 6y_2)} w_1 + \underline{(-6y_1 - 9y_2)} w_2 \\ &\quad + \underline{(7y_1 - 2y_2)} w_3 \\ &\leq 3w_1 - w_2 - 4w_3 \end{aligned}$$

$$\begin{bmatrix} 5y_1 + 6y_2 \leq 3 \\ -6y_1 - 9y_2 \leq -1 \\ 7y_1 - 2y_2 \leq -4 \\ y_2 \geq 0 \end{bmatrix}$$

Then, $9y_1 - 7y_2$ ^{maximizing} gives a lower bound

for $3x_1 - x_2 - 4x_3$.

The new problem is the DUAL of the original PRIMAL problem.

PRIMAL
 constraint i : $\langle \vec{a}_i, \vec{x} \rangle = b_i$ ✓
 constraint i : $\langle \vec{a}_i, \vec{x} \rangle \geq b_i$ ✓
 var j : $\underbrace{x_j \geq 0}$ ✓
 var j : $x_j \geq 0$ ✓
 obj. fun. : $\min \langle \vec{c}, \vec{x} \rangle$ ✓

DUAL
 $\vec{y}_i \geq 0$ ✓
 $\vec{y}_i \geq 0$ ✓
 $(A^T \vec{y})_j = c_j$ ✓
 $(A^T \vec{y})_j \leq c_j$ ✓
 $\max \langle \vec{b}, \vec{y} \rangle$ ✓

Theorem: DUAL of the DUAL is the PRIMAL.

Proof. Exercise.

Duality theorems:

Theorem. (Weak duality theorem)

Let $\vec{x}$ be a feasible solⁿ to PRIMAL
and $\vec{y}$ be a feasible solⁿ to DUAL.

Then $\langle \vec{c}, \vec{x} \rangle \geq \langle \vec{b}', \vec{y} \rangle$.

Proof : $F \Rightarrow \langle A\bar{x} \leq b \rangle$

Since $\bar{x}$ is feasible, $A\bar{x} \leq b$.

Since y is feasible, $y \geq 0$, $A^T y = c$.

$$\langle b, y \rangle \stackrel{(y \geq 0)}{\leq} \langle A\bar{x}, y \rangle$$

$$= \langle \bar{x}, A^T y \rangle$$

$$= \langle \bar{x}, c \rangle$$

$$\begin{aligned} & \left(\langle A\bar{x}, y \rangle \right) \xrightarrow{\boxed{\bar{x}^T A^T y}} \\ & = \langle \bar{x}, A^T y \rangle \end{aligned}$$

Remark

α^*

→ optimal PRIMAL solⁿ

β^* → optimal DUAL solⁿ

$\alpha^* \geq \beta^*$

(Weak
duality)

(1) If $\alpha^* \leftarrow \infty$, then DUAL is
infeasible → PRIMAL is unbounded

(2) If $\beta^* \leftarrow \infty$, then PRIMAL is
infeasible → DUAL is unbounded

Theorem (Strong Duality)

If PRIMAL is feasible and bounded, then
DUAL is feasible and bounded, with
 $\alpha^* = \beta^*$.