

14/10/2021

Lecture - 8

Standard form of LP:

$$\begin{aligned} \min \quad & \langle \vec{c}, \vec{x} \rangle = \vec{c}^T \vec{x} \\ \text{subject to} \quad & \boxed{A \vec{x} = \vec{b}} \quad (\text{equality constraints}) \\ & \boxed{\vec{x} \geq \vec{0}} \quad (\text{sign constraints}) \end{aligned}$$

→ We can assume A is full-rank

$$\boxed{A} \rightarrow m \times n \text{ matrix}$$

dimension of $\vec{x}$

number of equality constraints

$$m \leq n \quad \text{and } m\text{-rank}(A)$$

$A_1, \dots, A_n \rightarrow$ columns of A .

$$\left[\begin{array}{ccc} & i_1 & i_n \\ & A_{j_1} & A_{j_n} \end{array} \right]$$

If $A_{j_1}, \dots, A_{j_n}$ are linearly independent,
 $(J = \{j_1, \dots, j_n\})$

$$A^{(J)} = [A_{j_1} \mid \dots \mid A_{j_n}]$$

$$A \vec{x} = \vec{b}$$

$$\vec{x} = [x_{j_1} \mid \dots \mid x_{j_n}]^T$$

$\rightarrow m \times n$ invertible matrix

$$x_J = A_J^{-1} \vec{b}$$

$$x_{J^c} = \vec{0}$$

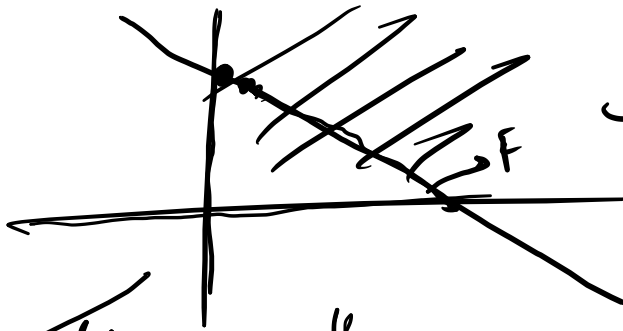
$$\underline{\underline{A \vec{x} = \left([A_J \mid A_{J^c}] \begin{bmatrix} x_J \\ x_{J^c} \end{bmatrix} \right)}}$$

$$= \underbrace{A_J x_J}_{\vec{b}} + \underbrace{A_{J^c} x_{J^c}}_{\vec{0}} = \vec{b}$$

$$= \vec{b} + \vec{0} = \vec{b}$$

$\vec{x} = [x_J \mid \vec{0}]$ is a basic solⁿ

If $\boxed{x_J \geq \vec{0}}$, $\vec{x}$ is a basic feasible solⁿ



$$\begin{array}{|c|} \hline x_1 \geq 0 \\ \hline x_2 \geq 0 \\ \hline \end{array}$$

Goal: If the feasible region of LPS
it must have a basic feasible soln.
↳ vertex.

is normally,
 $x_1 + t a_1, \dots, x_n + t a_n$
 $t \in \mathbb{R}_+$

Theorem. In LPS, suppose that $\vec{w} \in \mathbb{R}^n$.
 Then $\vec{w}$ is a vertex (or extreme point) of F
 if and only if $\vec{w}$ is a basic feasible
 solution of the LPS instance.

Proof. ($\Rightarrow$)

$\vec{w}$ is a vertex of F .

$$I = \{i : w_i > 0\}$$

Claim. $\{A_i : i \in I\}$ are linearly independent

$$\sum_{i \in I} \lambda_i A_i = 0 \quad \text{in } \mathbb{R}^m \quad A_i \geq 0$$

$$A(\vec{w} + \theta \vec{z}) = b \quad \text{for } \theta > 0$$

$\{A_j : j \in \underline{I}\}$ extends to a basis^(J) of $\mathbb{R}^n$.
 using columns of A .

$$w_j = 0 \text{ if } j \notin I$$

$$\Rightarrow w_j = 0 \text{ if } j \notin J \text{ (} \mathbb{J} \in \mathbb{J} \text{)}.$$

$$\left[A_1, \dots, A_m \right] \text{ is invertible.}$$

$\vec{w} = [w_1, w_2, \dots]$ and $\vec{w} \in \mathbb{F}$.

($\Leftarrow$) Let $\vec{w}$ be a bfs of

$$A\vec{x} = \vec{b}, \quad \vec{x} \geq \vec{0}, \quad (\text{LPS}).$$

where A has rank m .

Choose $J \subseteq \{1, 2, \dots, n\}$ corresponding
to $\vec{w}$. ($\#(J) = m$ and for $j \notin J$,

$$w_j = 0$$

[Furthermore, $\vec{w}$ is the unique vector
in $\mathbb{R}^n$ satisfying $w_j = 0$ if $j \notin J$.] $\checkmark$

Let $\boxed{\vec{w} := \frac{\vec{w}_1 + \vec{w}_2}{2}}$ for $\vec{w}_1, \vec{w}_2 \in \mathbb{F}$.

$w_{1,j} \geq 0, w_{2,j} \geq 0 \quad \forall j \in \{1, \dots, n\}$

$\textcircled{w_j} := \frac{w_{1,j} + w_{2,j}}{2}$

$\Rightarrow \underbrace{w_{1,j}} \geq 0, \underbrace{w_{2,j}} \geq 0 \quad \forall j \in \mathcal{J}^c$

By a previous remark, $\vec{w} = \vec{w}_1 = \vec{w}_2$.

Corollary. There are finitely many vertices
of LPS

Proof - Each vertex of T is a bfs.

bfs correspond to subsets of size m
 $i_1 < \dots < i_m$

$$m \in \{1, \dots, n\} \quad \left[A_{i_1} \mid \dots \mid A_{i_m} \right]$$

There are at most $\binom{n}{m}$ ~~lower~~ collection
of columns of A which form a basis of $\mathbb{R}^m$.
The number of bfs's is at most $\binom{n}{m}$.

Defn: A basic feasible soln is degenerate if it has ^{strictly} more than $n-m$ zeros.

$$\begin{bmatrix} A_1 & \dots & A_m \end{bmatrix}$$

* Degeneracy does not mean redundancy.

Theorem: If two different bases (from the column of A) correspond to a single bfs $\bar{v}$, then $\bar{v}$ is degenerate.

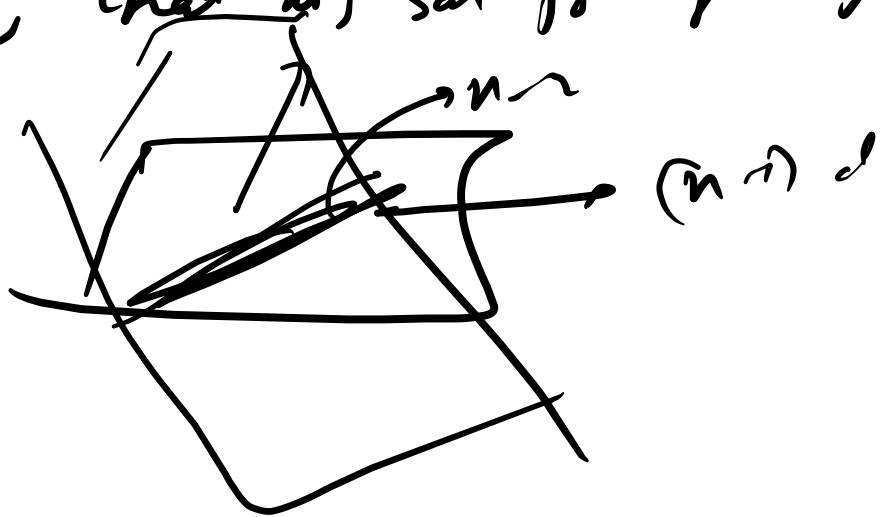
Pf - $J_1, A, \textcircled{J_2} \subseteq \{1, \dots, n\}$, $\#(J_1) = \#(J_2) = m$,
 $v_i = 0$ for $i \notin J_1 \cup J_2$, $v_i = 0$ for $i \notin J_2$.
 $(i \in J_1) \quad (i \in J_2^c)$

$v_j = 0$ for $j \notin J_1 \cap J_2$ ($j \in J_1 \cup J_2$
 $-(J_1 \cap J_2)$)

Hence, $v_j = 0$ for strictly more than
 $n-m$ indices j .

Exercise - If $\vec{v}$ is degenerate, is it necessarily
true that there are two different bases (comprised
of columns of A) corresponding to $\vec{v}$?
Prove or provide counterexample.

Lemma. Suppose $P = \{ \bar{x} \in \mathbb{R}^n \mid A\bar{x} \leq b \}$ is a polyhedron. Then $\bar{v}$ is an extreme point of P if and only if there are ~~to~~ $\boxed{n}$ linearly independent constraints (among $A\bar{x} \leq b$) that are tight at $\bar{v}$, that is, satisfy equality at $\bar{v}$.



Proof. ($\Rightarrow$)

Let $\bar{v}$ be an extreme point of P .

A $\textcircled{B} \bar{x} \leq \bar{b}$ be those constraints amongst $A \bar{x} \leq \bar{b}$ (B consists of a subset of rows of A) that are tight at $\bar{v}$.

$$B \bar{v} = \bar{b}$$

$$C \bar{v} < \bar{b}''$$

Claim - $\text{rank}(B) = n$

Proof of Claim: $\text{rank}(B) \leq n-1$

Choose $\bar{w} \in \text{nullspace of } B$
 $\downarrow$
 non-zero vector $\bar{v}' = \bar{v} + \bar{w}$

$$\textcircled{A \bar{x} \leq \bar{b}}$$

satisfies $B\bar{v}' = \bar{b}'$ for any $\gamma \in \mathbb{R}$

For a sufficiently small positive δ_6

both $\bar{v} + \delta_6 \bar{w}$ and $\bar{v} - \delta_6 \bar{w}$ satisfy the
remaining constraints.

$$\bar{v} \geq \frac{1}{2} (\bar{v} + \delta_6 \bar{w})$$

$$\leq \frac{1}{2} (\bar{v} - \delta_6 \bar{w})$$

$$\stackrel{\text{Q}}{\implies} c_1 x_1 + \dots + c_m x_m < \alpha_i$$

contradicting the fact that $\bar{v}$ is extreme.

Q

($\Leftarrow$) $\boxed{B\vec{x} \leq \vec{b}'}$ are tight at $\vec{v}$,
 and $\text{rank}(B) = n$.

$$\vec{v} = \frac{\vec{v}_1 + \vec{v}_2}{2} \quad \text{where } \vec{v}_1, \vec{v}_2 \in P$$

$$\vec{b}' = B\vec{v} = \frac{1}{2} B\vec{v}_1 + \frac{1}{2} B\vec{v}_2 \leq \frac{1}{2} \vec{b}' + \frac{1}{2} \vec{b}' = \vec{b}'$$

$\Rightarrow \vec{v} = \frac{\vec{v}_1 + \vec{v}_2}{2}$ is an extreme point of P

Defn: We say that a minimization problem is **unbounded** if for each real B , there is a feasible point of cost strictly less than B .

Theorem: In LPS, suppose that $\bar{p} \in \mathbb{R}^n$.

Then either LPS instance is unbounded or there is a vertex $\bar{v}$ of F

satisfying $\langle \bar{c}, \bar{v} \rangle \leq \bar{c}^T \bar{p}$ $\langle \bar{c}, \bar{p} \rangle$

(either there is no optimal solution or there is an optimal vertex.)

Corollary - If in LPS, $F \neq \emptyset$ and $\vec{c}^T \vec{x} \geq B$ for all $\vec{x} \in F$, then there is an optimal vertex. (Provided that the cost function is bounded below, LP is a finite problem).

Proof - $\vec{p} \in F$. Find $\vec{v}_1$ s.t. $\boxed{\langle \vec{c}, \vec{v}_1 \rangle} \leq \vec{p}$.
 If $\langle \vec{c}, \vec{v}_1 \rangle$ is minimum, we are done.

If not, $\exists \vec{p}_2 \in F$ s.t. $\langle \vec{c}, \vec{p}_2 \rangle < \langle \vec{c}, \vec{v}_1 \rangle$
 $\dots < \langle \vec{c}, \vec{p}_n \rangle < \langle \vec{c}, \vec{v}_1 \rangle$