

Class on 24 Aug:

QR Factorization:

Thm Let $A \in M_n(\mathbb{R})$ be invertible. Then there exists an orthogonal matrix Q and an upper triangular matrix R s.t. $A = QR$. This decomposition is unique ^{upto scaling of rows by ± 1} (may not be unique when A is non-singular).

Pf: Uniqueness: Let there be two decompositions Q_1, R_1 and Q_2, R_2 .

$$Q_1 R_1 = Q_2 R_2$$

$$\underbrace{Q_2^{-1} Q_1}_{\text{orthogonal}} = \underbrace{R_2 R_1^{-1}}_{\text{upper } \Delta^r} = T$$

This is only possible when the matrix T is diagonal with each diagonal entry ± 1 .

Existence: Let $\vec{a}_1, \dots, \vec{a}_n$ be column vectors of A .

$$\begin{aligned} \vec{u}_1 &:= \vec{a}_1, & \vec{u}_2 &:= \vec{a}_2 - (\text{projection of } \vec{a}_2 \text{ onto } \vec{u}_1) \\ \vec{u}_3 &:= \vec{a}_3 - (\text{proj. of } \vec{a}_3 \text{ onto } \vec{u}_2 + \text{proj. of } \vec{a}_3 \text{ onto } \vec{u}_1) \end{aligned}$$

$$\text{Let } \vec{u}_1 = \vec{a}_1$$

$$\vec{u}_2 = \vec{a}_2 - r_{12} \vec{u}_1 - r_{23} \vec{u}_2$$

$\vdots$

$$\vec{u}_n = \vec{a}_n - r_{1n} \vec{u}_1 - r_{2n} \vec{u}_2 - \dots - r_{n-1,n} \vec{u}_{n-1}$$

$$\therefore \vec{a}_1 = \vec{u}_1$$

$$\vec{a}_2 = \vec{u}_2 + r_{12} \vec{u}_1$$

$$\vec{a}_3 = \vec{u}_3 + r_{13} \vec{u}_1 + r_{23} \vec{u}_2$$

$\vdots$

$$\vec{a}_n = \vec{u}_n + r_{1n} \vec{u}_1 + \dots + r_{n-1,n} \vec{u}_{n-1}$$

In matrix form:

$$[\vec{a}_1 | \vec{a}_2 | \dots | \vec{a}_n] = [\vec{u}_1 | \vec{u}_2 | \dots | \vec{u}_n] \begin{bmatrix} r_{11} & r_{12} & r_{13} & \dots & r_{1n} \\ 0 & r_{22} & & & \\ \vdots & & \ddots & & \\ 0 & & & r_{n-1,n-1} & \\ 0 & & & & 1 \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} \frac{\vec{u}_1}{\|\vec{u}_1\|} & \frac{\vec{u}_2}{\|\vec{u}_2\|} & \dots & \frac{\vec{u}_n}{\|\vec{u}_n\|} \end{bmatrix}}_Q \underbrace{\begin{bmatrix} \|\vec{u}_1\| & \|\vec{u}_1\| r_{12} & \|\vec{u}_1\| r_{13} & \dots & \|\vec{u}_1\| r_{1n} \\ 0 & \|\vec{u}_2\| & \|\vec{u}_2\| r_{23} & & \\ & 0 & \|\vec{u}_3\| & & \\ & & & \ddots & \\ 0 & & & & \|\vec{u}_n\| \end{bmatrix}}_R$$

* Disadvantages of Gram-Schmidt process:

- Small imprecisions in the calculation of inner products can accumulate and lead to 'effective' loss of orthogonality.

Other Q-R Decompositions:

Find a sequence of Q_i 's st $Q_k \cdots Q_1 A = R$.

Precisely the transpose of the ' Q ' we are looking for.

We can find these from a sequence of "row operations" which eliminate some entries below the main diagonal.

Two types of orthogonal transformations: rotations and reflections.

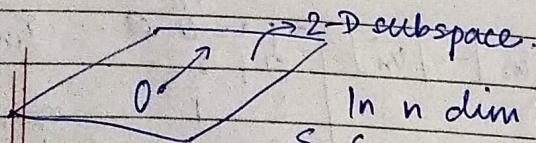
Given Rotations:

$$\Omega_{[e_i, e_j]} := \begin{bmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & \ddots & & \\ & & & & \cos \theta & \sin \theta \\ & & & & -\sin \theta & \cos \theta \\ & & & & & \ddots \\ & & & & & & 1 \end{bmatrix}$$

This represents a rotation of $\text{span}[e_i, e_j]$.

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & \\ \vdots & \\ a_{n1} & \end{bmatrix} \quad a_{nn}$$

If $a_{11} \neq 0$ (using permutations)



In n dim:

$$\{ (0, x_2, \dots, x_n) : x_i \in \mathbb{R}, 2 \leq i \leq n-1 \}.$$

is an $n-1$ dimensional subspace

[2] This distinction is clear in 3×3 matrices, but in higher dimensions ~~they~~ it becomes unclear.

We want θ s.t.
$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & & a_{2n} \\ \vdots & & \vdots \end{bmatrix}$$

gives $a_{11} \cos \theta + a_{21} \sin \theta = 0 \Rightarrow \cot \theta = \frac{-a_{21}}{a_{11}}$

This method is useful for sparse matrices.

(Since you have to find Q_i for each non-zero entry below the main diagonal, $\sim \binom{n}{2}$ calculations. - This number is much lesser for sparse matrices).

Householder Reflections:

Take $\vec{v} \neq \vec{0} \in \mathbb{R}^n$.

Reflection along $\underbrace{[\vec{v}]}_{\text{Span of } \vec{v}}$ takes $\vec{v}$ to $-\vec{v}$,
 $\vec{x} \in \vec{v}^\perp$ to $\vec{x}$.

Similarly, reflection along $[\vec{v}^\perp]$ takes $\vec{v}$ to $-\vec{v}$,
 $\vec{x} \in \{\vec{v}\}^\perp$ to $\vec{x}$.

$$H_{\vec{v}} = I - \frac{2\vec{v}\vec{v}^T}{\|\vec{v}\|^2}$$

Fact: S is a reflection iff $\frac{I+S}{2}$ is a projection.

- Given a reflection operator S , you can recover the subspace along which reflection occurs by looking at the eigenspace corresponding to eigenvalue 1.
- Reflections are self-adjoint.

Thm: Let $R \in M_n(\mathbb{R})$. The R is a reflection iff $\frac{I+R}{2}$ is a projection.

Pf: $R^2 = I \Leftrightarrow \left(\frac{I+R}{2}\right)^2 = \frac{I+R^2+2R}{4} = \frac{I+R}{2}$.

Assume $\|\vec{v}\|=1$. Then:

Projection onto $\{\vec{v}\} = I - \vec{v}\vec{v}^T$ ($\|\vec{v}\|=1$).

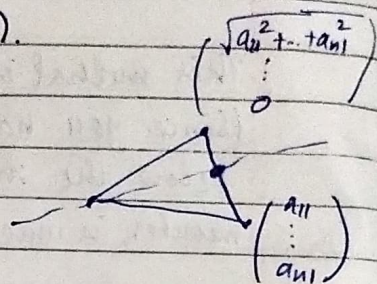
Reflection about $\{\vec{v}\}^\perp = 2(I - \vec{v}\vec{v}^T) - I$
 $= I - 2\vec{v}\vec{v}^T = H_{\vec{v}}$.

We want Q_i 's st. $Q_k \dots Q_1 A = R$.

Find H_v to convert $\begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix}$ to $\begin{bmatrix} r_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ --- (2)

(If this is possible then $|r_1| = \|\vec{a}_{*1}\|$).

Choose $\vec{v}_1 = \begin{bmatrix} a_{11} + \sqrt{a_{11}^2 + a_{21}^2 + \dots + a_{n1}^2} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix}$



$H_{v_1} = Q_{11}$
 $= \frac{I - 2 \vec{v}_1 \vec{v}_1^T}{\|\vec{v}_1\|^2}$

Once a_{*1} is converted to the form stated in (2), then

H_{v_2} is chosen for:

$\begin{bmatrix} r_1 & * & * & * & * \\ 0 & r_2 & & & \\ 0 & 0 & & & \\ \vdots & \vdots & & & \\ 0 & 0 & & & \end{bmatrix}$

converting a smaller column to the form $\begin{bmatrix} r_2 \\ 0 \\ \vdots \\ 0 \end{bmatrix}_{n-1 \times 1}$.

$\therefore H_{v_n} \dots H_{v_1} A = R$

You prove this by induction.

- This method is good for non-sparse matrices too.

Cor: Every orthogonal matrix on $M_n(\mathbb{R})$ can be decomposed into the product of 'n' reflections. (Cartan-Dieudonné Theorem)

In the complex case: $R^2 = I$, $R = R^*$ hold.

Can we write unitary matrices as the product of 'n' reflections?

Take $\begin{bmatrix} \omega & 0 \\ 0 & \omega \end{bmatrix} = R_1 \dots R_n$. (ω : cube root of unity)

det of RHS = ± 1 , det of LHS = ω^2 which are not equal.

Thm (Radjan): A unitary matrix U in $M_n(\mathbb{C})$ is the product of four reflections iff $\det(U) = \pm 1$.
(says that the only obstruction to writing a unitary matrix as a product of reflections is the one imposed by the det).

Thm (Halmos-Kakutani): Every unitary operator in $B(\mathcal{H})$ ($\mathcal{H}$: infinite dimensional) can be decomposed as the product of four reflections.

Exc. Let $\alpha: X \rightarrow X$ be a bijection. Then there are bijections β_1, β_2 s.t. $\beta_1^2 = \text{Id}$, $\beta_2^2 = \text{Id}$ (called involutions) and $\alpha = \beta_1 \circ \beta_2$.

Take G : locally compact (topological) group
(loc. compact: means every pt. has a nhbd whose closure is compact).

- Examples:
1. $G = (\mathbb{R}^n, +)$ with Euclidean topology.
 2. $G = O_n(\mathbb{R}) \subset M_n(\mathbb{R})$ with subsp. top.
 3. $G = (\mathbb{Z}, +)$ with discrete top.
 4. $G = (S^1, \circ)$ with subsp. top.

Defn: A Radon measure μ on the Borel σ -algebra of G is said to be a left-invariant Haar measure if $\mu(g \cdot E) = \mu(E)$ for all measurable sets E in σ_G .

Thm: Every locally compact group has a left-invariant measure, (unique upto positive scalar multiples).

Examples: 3. $G = (\mathbb{Z}, +)$ with discrete top: the counting measure is a left-invariant Haar measure.

4. $G = (S^1, \circ)$ with subsp. top: Lebesgue measure

Uniform Sampling from G :

If $S = \{g_1, \dots, g_n\}$ is a sample, then it is "uniform" if

$$\#(E \cap S) \approx \#(g \cdot E \cap S), \quad \text{where } E \text{ is a nhbd of identity in } G.$$