Some Applications of the Power Watershed Framework to Image Segmentation and Image Filtering

Sravan Danda*

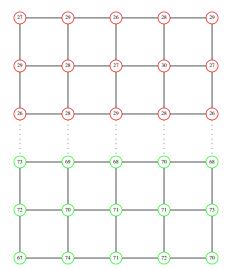
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October 11, 2019

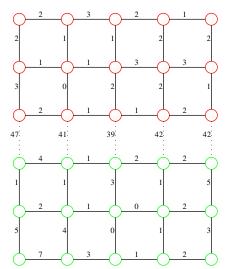
Overview

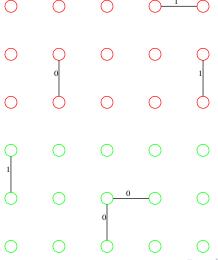
- 1 Watershed Segmentation on Graphs
- 2 Power Watershed (PW) Framework
- 3 PW for Fast Isoperimetric Image Segmentation
- 4 Mutex Watershed : PW Limit of Multi-Cut Graph Partitioning
- 5 PW for Image Filtering
- 6 Perspectives

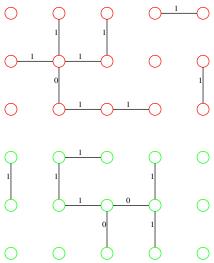
A synthetic gray-scale image

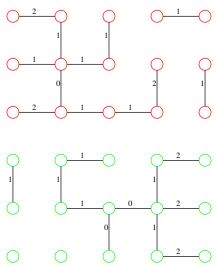


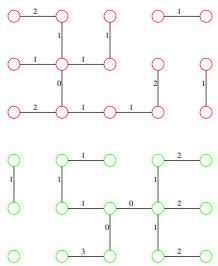
Gradient Image

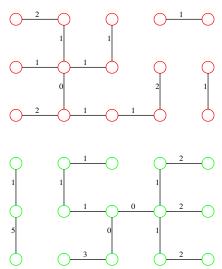












Watershed as a Graph-cut

Watershed Cut:

■ Minimum Spanning Forest Cut w.r.t. Minima ¹

Watershed as a Limit of Total Variation Minimizers

Power Watershed ²

 \blacksquare $\lim_{p\to\infty} \mathbf{x}^{(p)}$ where

$$\mathbf{x}^{(p)} = \underset{\mathbf{x}}{\operatorname{arg min}}(Q^{(p)}(\mathbf{x}))$$

$$Q^{(p)}(\mathbf{x}) = \sum_{i \in S} w_{ij}^{p} |x_i - x_j|^2 + \sum_{i \in S} w_i^{p} |x_i - f_i|^2$$

²Power watershed: A unifying graph-based optimization framework, C Couprie, L Grady, L Najman, H Talbot, IEEE transactions on pattern analysis and machine intelligence 33 (7), 1384-1399

Power Watershed: Fast Watershed Cut



Power Watershed: Seeded Image Segmentation ³

³Power watershed: A unifying graph-based optimization framework, C Couprie, L Grady, L Najman, H Talbot, IEEE transactions on pattern analysis and machine intelligence 33 (7), 1384-1399

Let
$$0<\lambda_1<\lambda_2<\cdots<\lambda_k$$

$$Q(\mathbf{x})=\sum_i\lambda_iQ_i(\mathbf{x})$$

Let
$$0<\lambda_1<\lambda_2<\cdots<\lambda_k$$

$$Q^{(p)}(\mathbf{x})=\sum_i\lambda_i^pQ_i(\mathbf{x})$$

Let
$$0<\lambda_1<\lambda_2<\cdots<\lambda_k$$

$$Q^{(\rho)}(\mathbf{x})=\sum_i\lambda_i^\rho Q_i(\mathbf{x})$$

$$\mathbf{x}^{(\rho)}=\arg\min_{\mathbf{x}}Q^{(\rho)}(\mathbf{x})$$

Let
$$0<\lambda_1<\lambda_2<\cdots<\lambda_k$$

$$Q^{(p)}(\mathbf{x})=\sum_i\lambda_i^pQ_i(\mathbf{x})$$

$$\mathbf{x}^{(p)}=\arg\min_{\mathbf{x}}Q^{(p)}(\mathbf{x})$$

$$\mathbf{x}^{(p)}\to\mathbf{x}^* \quad (?)$$

Power Watershed - Generic Algorithm

Algorithm 1 Generic Algorithm to compute limit of minimizers ⁴

Input: Function
$$Q^{(p)}(\mathbf{x}) = \sum_{i=1}^k \lambda_i^p Q_i(\mathbf{x})$$
, where $\lambda_k > \lambda_{k-1} > \cdots > \lambda_1 > 0$.

Output: x*:

- 1: $M_k = \arg \min Q_k(\mathbf{x})$ where $\mathbf{x} \in C$
- 2: **for** *i* from k 1 to 1 **do**
- 3: Compute $M_i = \arg\min Q_i(\mathbf{x})$ where $\mathbf{x} \in M_{i+1}$
- 4: end for

 $^{^4}$ Extending the Power Watershed Framework Thanks to Γ -Convergence,L

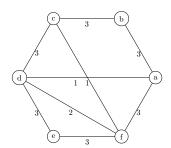
Power Watershed Framework - Why?

 Relates Watershed-Cuts with Random Walker and Shortest Path Segmentation

Power Watershed Framework - Why?

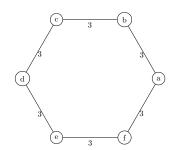
- Relates Watershed-Cuts with Random Walker and Shortest Path Segmentation
- Results in a faster Watershed-Cut algorithm

Laplacian Matrix

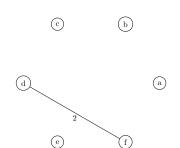


Fast Spectral Clustering using PW Framework

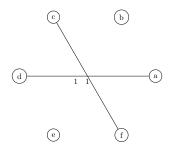
Laplacian Matrix: Decomposition



Laplacian Matrix: Decomposition



Laplacian Matrix: Decomposition



Fast Spectral Clustering using PW Framework

minimize
$$H \in \mathbb{R}^{n \times m}$$
 $\sum_{i} w_{i}^{p} Tr(H^{t} L_{i} H)$
subject to $H^{t} H = I$
(2)

Scalability of Spectral Clustering Algorithms

■ Traditional Spectral Clustering: $\mathcal{O}(n^{\frac{3}{2}})$

where n are non-zero entries in L

Scalability of Spectral Clustering Algorithms

- Traditional Spectral Clustering: $\mathcal{O}(n^{\frac{3}{2}})$
- Power Spectral Clustering: $\mathcal{O}(nlogn)$

where *n* are non-zero entries in *L*

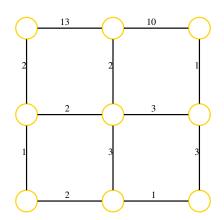
PW Framework for other Image Segmentation Algorithms?

Can we obtain faster algorithms for other image segmentation methods?

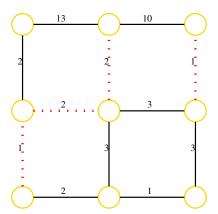
PW Framework for other Image Segmentation Algorithms?

- Can we obtain faster algorithms for other image segmentation methods?
- Yes!

Image: Similarity Graph



$$w_{ij} = 100 \exp(-\frac{||i-j||}{\sigma})$$



Isoperimetric
$$Cost(A) = \frac{W(A, \overline{A})}{\min\{|A|, n - |A|\}}$$

$$x_i = \begin{cases} 0 & \text{if } v_i \in A \\ 1 & \text{if } v_i \in \overline{A} \end{cases}$$

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$$\mathbf{x}^{t} L \mathbf{x} = \mathbf{x}^{t} D \mathbf{x} - \mathbf{x}^{t} W \mathbf{x}$$

$$= \sum_{i,j} x_{i} d_{ij} x_{j} - \sum_{i,j} x_{i} w_{ij} x_{j}$$

$$= \sum_{i,j} w_{ij} x_{i}^{2} - \sum_{i,j} x_{i} w_{ij} x_{j}$$

$$= \sum_{i,j} w_{ij} (x_{i}^{2} - 2x_{i} x_{j} + x_{j}^{2})$$

$$= \sum_{i,j} w_{ij} (x_{i} - x_{j})^{2}$$

$$x_i = \begin{cases} 0 & \text{if } v_i \in A \\ 1 & \text{if } v_i \in \overline{A} \end{cases}$$
$$\mathbf{x}^t L \mathbf{x} = W(A, \overline{A})$$

$$x_i = \begin{cases} 0 & \text{if } v_i \in A \\ 1 & \text{if } v_i \in \overline{A} \end{cases}$$
$$|A| = \mathbf{x}^t \mathbf{1}$$
$$n - |A| = (\mathbf{1} - \mathbf{x})^t \mathbf{1}$$

Discrete Formulation:

minimize
$$\frac{\mathbf{x}^t L \mathbf{x}}{\min{\{\mathbf{x}^t \mathbf{1}, (\mathbf{1} - \mathbf{x})^t \mathbf{1}\}}}$$
 subject to $x_i \in \{0, 1\} \ \forall i$

Continuous Relaxation:

minimize
$$\frac{\mathbf{x}^t L \mathbf{x}}{\min{\{\mathbf{x}^t \mathbf{1}, (\mathbf{1} - \mathbf{x})^t \mathbf{1}\}}}$$
 subject to $x_i \in [0, 1] \ \forall i$ (3)

Select best threshold!

Seed Constraint $x_j = 0$

minimize
$$\frac{\mathbf{x}_{-j}^{t} L_{-j} \mathbf{x}_{-j}}{\min \{\mathbf{x}_{-j}^{t} \mathbf{1}, (\mathbf{1} - \mathbf{x}_{-j})^{t} \mathbf{1}\}}$$
 subject to $x_{i} \in [0, 1]$ for $i \neq j$

Select best threshold!

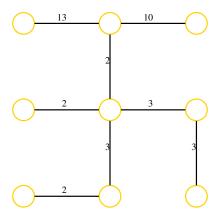
Lagrange Multipliers ⁵

$$L_{-j}\mathbf{x}_{-j}=\mathbf{1} \tag{3}$$

⁵Isoperimetric graph partitioning for image segmentation, L Grady, EL Schwartz, IEEE Transactions on Pattern Analysis and Machine Intelligence, 469-475

$$L_{-j}^{MaxST}\mathbf{x}_{-j}=\mathbf{1} \tag{4}$$

⁶Fast, quality, segmentation of large volumes - isoperimetric distance trees, L Grady, European Conference on Computer Vision, 449-462_{→ + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2 → + 2}



PW for Fast Isoperimetric Image Segmentation

 $\mathcal{O}(n)$: where n are non-zero entries in L

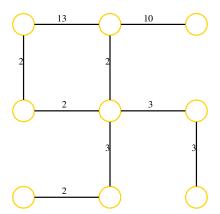
Fast Isoperimetric Partitioning: Computational Cost

Why does the MST heuristic work?

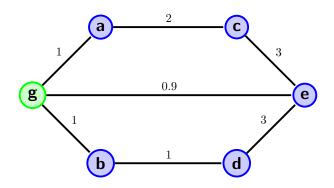
Power Watershed Framework \Rightarrow Enough to solve on UMaxST! ⁷

⁷Revisiting the Isoperimetric Graph Partitioning Problem, **S Danda**, A Challa, BD Sagar, L Najman, available at https://hal.archives-ouvertes.fr/hal-01810249

Fast Isoperimetric Partitioning Using PW

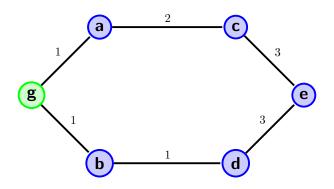


Are Solutions on MST and UMST the same?



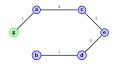
Original Graph

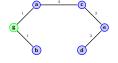
Are Solutions on MST and UMST the same?

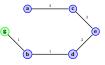


UMST Graph

Are Solutions on MST and UMST the same?







All Possible MSTs

Solving Linear System on Graph, UMST and an arbitrary MST are different!

Node	Original	UMST	MST_1	MST_2	MST_3
g	0.00	0.00	0.00	0.00	0.00
а	1.69	2.68	5.00	4.00	11.16
Ь	1.54	2.32	9.66	1.00	5.00
С	2.04	3.52	7.00	5.50	10.66
d	2.09	3.64	8.66	6.50	9.00
e	1.94	3.74	8.00	6.16	10.00

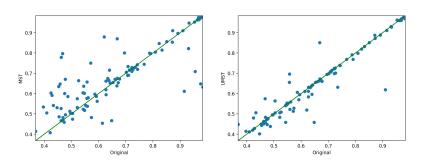
How different are Solutions on MST and UMST?

Lemma

Let T_{umst} and T_{mst} denote the operators on UMST and MST respectively, as defined above. Then there exists two positive constants K_1 and K_2 such that

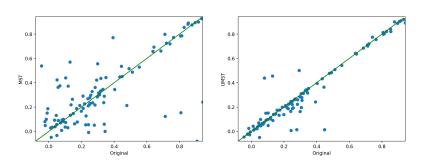
$$K_1 \sum_{i=1}^{k} (u_i - m_i)^2 w_i^2 \le ||T_{umst} - T_{mst}|| \le K_2 \sum_{i=1}^{k} (u_i - m_i)^2 w_i^2.$$
 (5)

F-Score



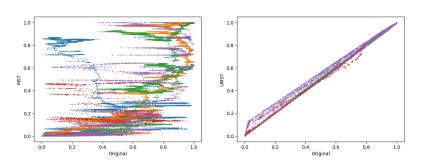
Comparison of MaxST and UMaxST as a sufficient statistic!

Adjusted Rand Index



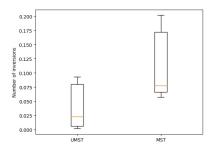
Comparison of MaxST and UMaxST as a sufficient statistic!

Scatter plot of Normalized values of solutions



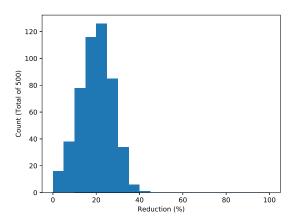
Strictly increasing plot implies perfectly consistent solutions!

Inversions



Comparison of MaxST and UMaxST as a sufficient statistic!

Data Reduction



- 1 Detailed Analysis of the relaxed Cheeger Cut problem
- 2
- 3
- 4

- Detailed Analysis of the relaxed Cheeger Cut problem
- 2 Establish using PW framework that considering UMST graph acts as a sufficient statistic
- 3
- 4

- Detailed Analysis of the relaxed Cheeger Cut problem
- Establish using PW framework that considering UMST graph acts as a sufficient statistic
- Establish bounds between UMST and MST based implementations
- 4

- Detailed Analysis of the relaxed Cheeger Cut problem
- 2 Establish using PW framework that considering UMST graph acts as a sufficient statistic
- Establish bounds between UMST and MST based implementations
- Empirically establish that UMST based reduction is robust compared to MST based implementation

Mutex Watershed: 8 The Setup

$$\mathcal{G} = (V, E, W)$$

^{*}Steffen Wolf, Constantin Pape, Alberto Bailoni, Nasim Rahaman, Anna Kreshuk, Ullrich Kothe, and Fred A. Hamprecht. The mutex watershed:

Efficient, parameter-free image partitioning. In Vittorio Ferrari, Martial Hebert, Cristian Sminchisescu, and Yair Weiss, editors, Computer Vision - ECCV 2018 - 15th European Conference, Munich, Germany, September 8-14, 2018, Proceedings, Part 4, volume 11208 of Lecture Notes in Computer Science, pages 571–587. Springer, 2018

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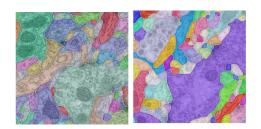
Mutex Watershed: 8 The Setup

- $\mathcal{G} = (V, E, W)$
- $f: E \to \{-1, +1\}$
- $lacksquare W:E
 ightarrow\mathbb{R}^+$

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Mutex Watershed: State-of-the-art on ISBI 2012



Mutex Watershed: Algorithm

Algorithm 2 Mutex Watershed

```
Initialize A=\emptyset.

for each edge e in descending order of W(e) do

if A\cup e does not violate the mutex condition then

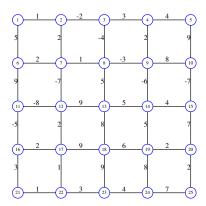
A\leftarrow A\cup e

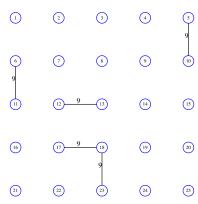
end if

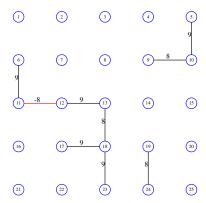
end for

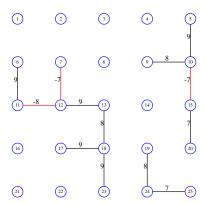
return Subgraph induced by \{e\in A|f(e)=+1\}
```

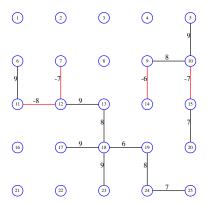
Mutex Watershed: An Example

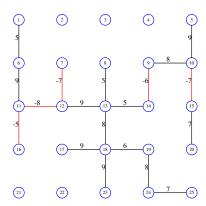


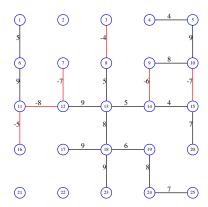


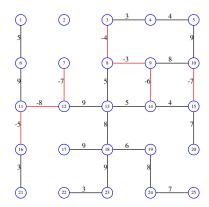




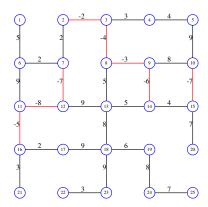




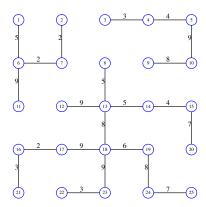




Mutex Watershed: Walk-Through



Mutex Watershed: Segments



Multi-Cut Graph Partitioning

$$Q(a) = \min_{a \in \{0,1\}^{|E|}} -\sum_{e \in E} a_e w_e$$

$$s.t \qquad C_1(A) = \emptyset \text{ with } A = \{e \in E | a_e = 1\}$$

$$(6)$$

NP-Hard!

$$Q^{(p)}(a) = \min_{a \in \{0,1\}^{|E|}} - \sum_{e \in E} a_e w_e^p$$

$$s.t \qquad C_1(A) = \emptyset \text{ with } A = \{e \in E | a_e = 1\}$$

$$(7)$$

$$\mathcal{G}_{k} = (V, E_{k}, W|_{E_{k}})$$

$$\min_{a \in \{0,1\}^{|E_{k}|}} - \sum_{e \in E_{k}} a_{e}$$

$$s.t \qquad \mathcal{C}_{1}(A) = \emptyset \text{ with } A = \{e \in E_{k} | a_{e} = 1\}$$

$$(8)$$

denote the solution space by A_k .

$$\mathcal{G}_{k-1} = (V, E_{k-1}, W|_{E_{k-1}})$$

$$\min_{a \in \{0,1\}^{|E_{k-1}|}} - \sum_{e \in E_{k-1}} a_e$$

$$s.t \qquad \mathcal{C}_1(A) = \emptyset \text{ with } A = A_k \cup \{e \in E_{k-1} | a_e = 1\}$$
(9)

denote the solution space by A_{k-1} .

Repeat until all edges are processed.

 Sub-problems can be handled with a 'Union-Find' data structure.

- Sub-problems can be handled with a 'Union-Find' data structure.
- Sub-problems are tractable!

Mutex Watershed is PW limit of Multi-cut partitioning

PW Framework for Image Filtering?

■ Can we relate image filtering tools?

PW Framework for Image Filtering?

- Can we relate image filtering tools?
- Yes!

Shortest Path Filter

$$SPF_i = \sum_{j \in V} g_i(j)I_j$$
,

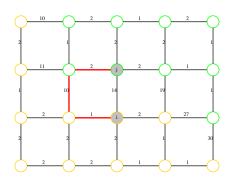
Shortest Path Filter

$$SPF_i = \sum_{j \in V} g_i(j)I_j$$
,

where

$$g_i(j) = \frac{\exp\left(-\frac{\Theta(i,j)}{\sigma}\right)}{\sum_{k \in V} \exp\left(-\frac{\Theta(i,k)}{\sigma}\right)}$$

Shortest Path Filter



$$\Theta_i(j) = 3$$

Tree Filter 9

$$\mathsf{TF}_i = \sum_j t_i(j) I_j$$

⁹Linchao Bao, Yibing Song, Qingxiong Yang, Hao Yuan, and Gang Wang. Tree filtering: Efficient structure-preserving smoothing with a minimum spanning tree. IEEE TIP, 23(2): 555-569, 2014.

Tree Filter 9

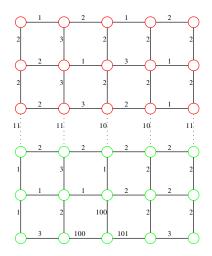
$$\mathsf{TF}_i = \sum_j t_i(j) I_j$$

where

$$t_i(j) = \frac{\exp(-\frac{D(i,j)}{\sigma})}{\sum_{q} \exp(-\frac{D(i,q)}{\sigma})}$$

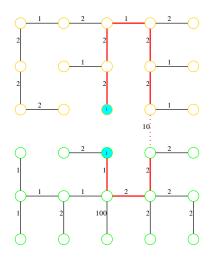
⁹Linchao Bao, Yibing Song, Qingxiong Yang, Hao Yuan, and Gang Wang. Tree filtering: Efficient structure-preserving smoothing with a minimum spanning tree. IEEE TIP, 23(2): 555-569, 2014.

Tree Filter on a Synthetic Graph



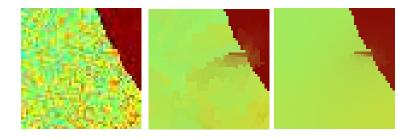
Gradient image

Tree Filter on a Synthetic Graph



$$t_i(j) = 9$$

Tree Filter on a Synthetic Image



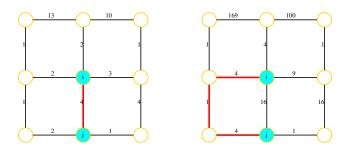
L to R: Noisy Image, TF, TF + BF

Can the Tree Filter be explained?

Power Watershed Framework \Rightarrow Tree Filter is an approximate limit of Shortest Path Filters 10

¹⁰ Some Theoretical Links between Shortest Path Filters and Minimum Spanning Tree Filters, **S Danda**, A Challa, BD Sagar, L Najman, Journal of Mathematical Imaging and Vision, January 2019

Limit of Shortest Path Filters



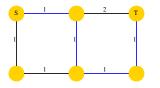
L to R: Image Graph, Image Graph with edge weights raised to power 2

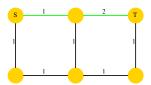
Limit of Shortest Path Filters: Characterization

Lemma

Let $\mathcal{G} = (V, E, W)$. For every pair of pixels i and j in V, there exists $p_0 \geq 1$ such that, a path P(i,j) is a shortest path between i and j in $\mathcal{G}^{(p)}$ for all $p \geq p_0$ if and only if P(i,j) is a smallest path w.r.t. reverse dictionary order between i and j in \mathcal{G} . Further, p_0 is independent of i and j.

Reverse Dictionary Order: Illustration



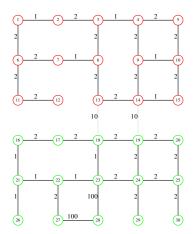


Limit of Shortest Path Filters: Characterization

Lemma

Every smallest path w.r.t. reverse dictionary order between any two arbitrary nodes in $\mathcal{G} = (V, E, W)$ lies on an MST of \mathcal{G} and hence on the UMST of \mathcal{G} .

Limit of Shortest Path Filters: UMST Filter

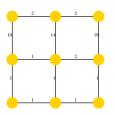


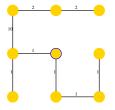
UMST Filter: Characterization

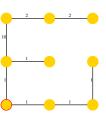
Lemma

For every pixel i in the image I, there exists a spanning tree T_i (termed as adaptive spanning tree), such that T_i contains a smallest path with respect to reverse dictionary ordering between pixels i and any other pixel j in I.

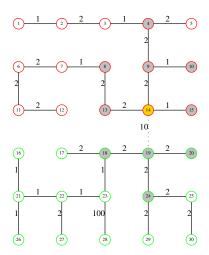
UMST Filter: Adaptive Spanning Trees



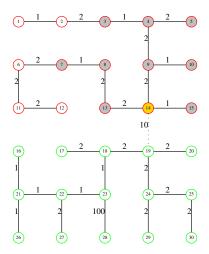




UMST Filter: Depth-Based Approximation



UMST Filter: Order-Based Approximation



Results in Practice

Salt and Pepper Noise



L to R: House Image, Bilateral Filter, Tree Filter, Our Approximation to Limit of SPFs

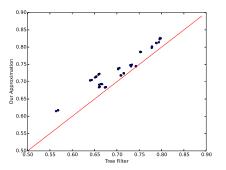
Results in Practice

Structural Similarity Indices

	Mean SSIM on Salt Pepper Noise		
	BF	TF	UMSTF
House	0.69	0.80	0.83
Barbara	0.72	0.66	0.72
Lena	0.69	0.75	0.79
Pepper	0.62	0.74	0.74
Mean	0.68	0.74	0.77

Results in Practice

SSIM: Tree Filter vs UMST Filter 11



¹¹Some theoretical links between shortest path filters and minimum spanning tree filters, **S Danda**, A Challa, BSD Sagar, L Najman, available at https://hal.archives-ouvertes.fr/hal-01617799v5

- 1 Establish UMST filter as a limit of shortest path filters
- 2
- 3

- 1 Establish UMST filter as a limit of shortest path filters
- 2 Tree filter as an approximation to UMST filter
- 3

- 1 Establish UMST filter as a limit of shortest path filters
- 2 Tree filter as an approximation to UMST filter
- Implement Depth-based and Order-based approximations of UMST filter

- 1 Adaptive Spanning Trees can be processed in parallel!
- 2

- 1 Adaptive Spanning Trees can be processed in parallel!
- 2 Can we learn edge-aware features using the adaptive spanning trees?

- **I** Can we speed-up other tree-based algorithms such as scale-set analysis?
- 2
- 3
- 4

- Can we speed-up other tree-based algorithms such as scale-set analysis?
- 2 Total Variation ↔ Cheeger Cut. Application to TV minimization!
- 3
- 4

- Can we speed-up other tree-based algorithms such as scale-set analysis?
- 2 Total Variation ↔ Cheeger Cut. Application to TV minimization!
- 3 Understanding working principle behind PW framework?
- 4

- Can we speed-up other tree-based algorithms such as scale-set analysis?
- 2 Total Variation ↔ Cheeger Cut. Application to TV minimization!
- Understanding working principle behind PW framework?
- 4 PW implies UMST is a sufficient statistic for image segmentation and filtering. Can we obtain sufficient statistics for graph-modelled data in general?

I would like to thank my advisors, Prof. B S Daya Sagar and Prof. Laurent Najman all their support, anonymous reviewers of my articles and anonymous examiners and CCSD faculty for their suggestions, and Indian Statistical Institute for providing me fellowship to pursue this research.