

01/02/16

LECTURE - 2

Recall:

$$\frac{\partial u}{\partial t} = -\Delta u \quad u(0, x) = \varphi(x), \quad x \in [0, 1]$$

$$u(t, 0) = u(t, 1) = 0.$$

(*)
$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = -\Delta u + f(t, x) \quad \rightarrow f(t, x) = \tilde{f}(t, x) - \text{space-time white noise.} \\ \frac{\partial u}{\partial t} = \Delta u + \sigma(u) \tilde{f}(t, x) + b(u) \quad \text{Additive noise.} \end{array} \right.$$

Multiplicative.

$\lambda = 0$, require u to be differentiable. But $\lambda > 0$, u might be rough. Need to make sense of (*).

Weak solution formulation: $\varphi \in C_c^\infty(\mathbb{R}_+ \times \mathbb{R})$ test functions.

$$-\int_0^\infty \int_{\mathbb{R}} u(t, x) \frac{\partial \varphi}{\partial t}(t, x) dt dx = \int_0^\infty \int_{\mathbb{R}} u(t, x) \Delta \varphi(t, x) dt dx$$

$$+ \lambda \underbrace{\int_0^\infty \int_{\mathbb{R}} \varphi(t, x) \tilde{f}(dt, dx)}_{\text{integral?}}$$

Multiplicative case:

$$\int_0^\infty \int_{\mathbb{R}} \sigma(u) \varphi(t, x) \tilde{f}(dt, dx) \quad \text{--- Stochastic Integrals?}$$

$u(t, x) := P_t * \phi(x)$ or $P_t(z) = \frac{e^{-z^2/2t}}{\sqrt{2\pi t}}$ } $\lambda = 0$ case in (*)

then $\frac{\partial u}{\partial t} = \frac{1}{2} \Delta u, \quad u(0, x) = \phi(x).$

$f(t, x)$ - deterministic. — (✓) Set-up.

$$u(t, x) := P_t * \phi(x) + \int_0^t \int_{\mathbb{R}} p_{t-s}(x-y) f(s, y) dy ds$$

then $\frac{du}{dt} = \Delta u + f \quad \& \quad u(0, x) = \phi(x).$

For $\otimes$ - random i.e., $f = \bar{z}$, random

Then solutions $u(t, x) = P_t * \phi(x) + \int_0^t \int_{\mathbb{R}} p_{t-s}(x-y) \bar{z}(dy, ds)$

is a "solution" (?) to "STOCHASTIC CONVOLUTION" (3)

$$\frac{\partial u}{\partial t} = \Delta u + \bar{z}, \quad u(0, x) = \phi(x), \quad t > 0, x \in \mathbb{R}$$

CH 2. (Davari's book.) T -set, Gaussian Random field on T .

$\{X_t\}_{t \in T}$ is GRF on T if $(X_{t_1}, \dots, X_{t_m})$ is a Gaussian vector in $m \geq 1, t_i \in T$.

$T \subseteq \mathbb{R}$ GRF = GProc.

White-noise on $\mathbb{R}^m$: $\mathcal{L}(\mathbb{R}^m) = \{B \subseteq \mathbb{R}^m \mid B \text{ Borel} \& |B| < \infty\}$

$\bar{z}$ - white noise on $\mathbb{R}^m$ if $\bar{z}$ is a $\mathcal{L}(\mathbb{R}^m)$ -indexed GRF with mean 0 & $\text{Cov}(\bar{z}(A), \bar{z}(B)) = |A \cap B|$

i.e., $\{\bar{z}(A)\}_{A \in \mathcal{L}(\mathbb{R}^m)} \rightarrow \mathbb{E} \bar{z}(A) = 0, \text{Cov}(\bar{z}(A), \bar{z}(B)) = |A \cap B|, \forall A, B \in \mathcal{L}(\mathbb{R}^m).$

EXISTENCE: $\alpha_1, \dots, \alpha_n \in \mathbb{C}, A_1, \dots, A_n \in \mathcal{L}(\mathbb{R}^m)$

$$\begin{aligned} \sum_{i,j=1}^n \alpha_i \bar{\alpha}_j \mathbb{1}_{A_i \cap A_j} &= \sum_{i,j} \alpha_i \bar{\alpha}_j \int_{\mathbb{R}^m} \mathbb{1}_{A_i} \mathbb{1}_{A_j} dx \\ &= \int_{\mathbb{R}^m} \sum_{i,j} \alpha_i \bar{\alpha}_j \mathbb{1}_{A_i} \mathbb{1}_{A_j} dx \\ &= \int_{\mathbb{R}^m} \left| \sum_i \alpha_i \mathbb{1}_{A_i} \right|^2 dx \geq 0. \end{aligned}$$

$\Rightarrow$ Cov. fn is positive semi-definite & hence white-noise exists.

PROPERTIES of $\bar{z}$: $\bar{z}(A) \stackrel{d}{=} N(0, |A|) \quad A \in \mathcal{L}(\mathbb{R}^m)$

$\bar{z}(A)$ & $\bar{z}(B)$ are indep if $A \cap B = \emptyset$

$$A_1 \cap A_2 = \emptyset$$

$$A_1, A_2 \in \mathcal{L}(\mathbb{R}^m).$$

$$\mathbb{E} |\bar{\lambda}(A_1 \cup A_2) - \bar{\lambda}(A_1) - \bar{\lambda}(A_2)|^2$$

$$= |A_1 \cup A_2| - |A_1| - |A_2| + 2|A_1 \cap A_2|$$

$$= 0 \text{ if } A_1 \cap A_2 = \emptyset.$$

$\bar{\lambda}$ is finitely additive in L^2 -sense.

$$B_1 \supseteq B_2 \supseteq \dots \Rightarrow \bigcap_{m=1}^{\infty} B_m = \emptyset \quad B_i \in \mathcal{L}(\mathbb{R}^m)$$

$$\mathbb{E} |\bar{\lambda}(B_n)|^2 = |B_n| \rightarrow 0 \text{ as } n \rightarrow \infty.$$

$$\Rightarrow A_i \in \mathcal{L}(\mathbb{R}^m), A_i \cap A_j = \emptyset \text{ then } \mathbb{E} \left| \bar{\lambda} \left(\bigcup_{i=1}^{\infty} A_i \right) - \sum_{i=1}^{\infty} \bar{\lambda}(A_i) \right|^2 = 0$$

$\bar{\lambda} = \mathcal{L}^2(\mathcal{L}, \mathcal{F}, P)$ valued σ -finite measure i.e., a σ -finite measure in the L^2 -sense.

[complete construction : Pg 286, Walsh Notes/Book].

$$\text{Ex. } m=1, \sum_{j=1}^{2^n} \left| \bar{\lambda} \left[\frac{j-1}{2^n}, \frac{j}{2^n} \right] \right|^2 \xrightarrow{P} 1 \text{ but } \sum_{j=1}^{2^n} \left| \bar{\lambda} \left[\frac{j-1}{2^n}, \frac{j}{2^n} \right] \right| \rightarrow \infty \text{ a.s.}$$

INTEGRATION OVER $\bar{\lambda}$ $S(\mathbb{R}^m) = \left\{ h: \mathbb{R}^m \rightarrow \mathbb{R} \mid h(x) = \sum_{i=1}^m \alpha_i \mathbb{1}_{A_i}(x), \right.$

$A_1, \dots, A_m \in \mathcal{L}(\mathbb{R}^m) \left. \right\}$

$$\int h d\bar{\lambda} = \int h(x) \bar{\lambda}(dx) = \sum_{i=1}^m \alpha_i \bar{\lambda}(A_i) \text{ or } h(x) = \sum_{i=1}^m \alpha_i \mathbb{1}_{A_i}(x)$$

PROP: Definition doesn't depend on representation of h .

$$\int (\alpha h + \beta g) d\bar{\lambda} = \alpha \int h d\bar{\lambda} + \beta \int g d\bar{\lambda} \quad h, g \in S(\mathbb{R}^m)$$

$\alpha, \beta \in \mathbb{R}.$

$$\left(\int h d\bar{\lambda} \right)_{h \in S(\mathbb{R}^m)} \text{ — GRF on } S(\mathbb{R}^m) \text{ with mean } 0.$$

$$\mathbb{E} \left[\int h d\bar{\lambda} \right] = 0 \quad \mathbb{E} \left[\int h_1 d\bar{\lambda} \int h_2 d\bar{\lambda} \right] = \mathbb{E} \left[\sum_{i=1}^m \sum_{j=1}^m \alpha_i \beta_j \mathbb{E} [\bar{\lambda}(A_i) \bar{\lambda}(B_j)] \right]$$

$$= \sum_{i=1}^m \sum_{j=1}^m \alpha_i \beta_j |A_i \cap B_j|$$

$$= \int_{\mathbb{R}} h_1(x) h_2(x) dx.$$

$$\Rightarrow E[(\int h_1 d\tilde{z} - \int h_2 d\tilde{z})^2] = \int |h_1 - h_2|^2 dx$$

$$h \in L^2(\mathbb{R}^m), \exists h_n \in S(\mathbb{R}^m) \rightarrow h \text{ in } L^2.$$

$$\Rightarrow E[(\int h_n d\tilde{z} - \int h_m d\tilde{z})^2] = \int |h_n - h_m|^2 dx$$

$$\Rightarrow (\int h_n d\tilde{z})_{n \geq 1} \text{ is Cauchy in } L^2(\Omega, \mathcal{F}, \mathbb{P})$$

$$\Rightarrow \int h d\tilde{z} = \lim_{n \rightarrow \infty} \int h_n d\tilde{z} \text{ in } L^2(\Omega, \mathcal{F}, \mathbb{P}).$$

Doesn't depend on choice of h .

$$\int (\alpha h + \beta g) d\tilde{z} = \alpha \int h d\tilde{z} + \beta \int g d\tilde{z}$$

$$(\int h d\tilde{z})_{h \in L^2(\mathbb{R}^m)} \text{ is a GRF on } L^2(\mathbb{R}^m).$$

$$E[\int h_1 d\tilde{z} \int h_2 d\tilde{z}] = \int h_1(x) h_2(x) dx. \quad E[\int h d\tilde{z}] = 0.$$

ISOMETRY:

$$L^2(\mathbb{R}^m) \longrightarrow L^2(\Omega, \mathcal{F}, \mathbb{P}).$$

$$h \xrightarrow{\text{Isometry.}} \int h d\tilde{z} \text{ - Wiener Integral.}$$

Stochastic Convolution : $x \in \mathbb{R}^m, f \in L^2(\mathbb{R}^m)$

$$f * \tilde{z}(x) = \int f(x-y) \tilde{z}(dy)$$

$$(\omega, x) \mapsto (f * \tilde{z})(\omega, x).$$

$$f \in C_c^\infty(\mathbb{R}^m) \quad E |f * \tilde{z}(x) - f * \tilde{z}(z)|^2 = E \left| \int (f(x-y) - f(z-y)) \tilde{z}(dy) \right|^2$$

$$= \int |f(x-y) - f(z-y)|^2 dy \leq c |x-z|^2$$

$$\Rightarrow x \mapsto E |f * \tilde{z}(x)|^2 \text{ is continuous in}$$

version of Kol. cty thm $\Rightarrow x \mapsto f * \tilde{z}(x)$ cts a.s.

Measure theoretic argument $\Rightarrow (\omega, x) \mapsto f * \tilde{z}(\omega, x)$ is jointly measurable.

Approximate $f \in L^2(\mathbb{R}^m)$ -

EXAMPLES: $m=1$. ξ - white noise on $\mathbb{R}$. $t \in [0, \infty)$

$$B_t = \xi([0, t]) \Rightarrow B_t \stackrel{d}{=} N(0, t) \quad \left. \begin{array}{l} \text{Continuous version} \\ \mathbb{E}[B_t B_s] = s \wedge t \end{array} \right\} \text{ is the SBM.}$$

$m=2$. $\psi^{(t)}: \mathbb{R}_+ \times \mathbb{R} \rightarrow \mathbb{R}$ fix $t > 0$

$$\psi^{(t)}(s, x) = 1_{[0, t]}(s) \phi(x) \quad \phi \in C_c^\infty(\mathbb{R})$$

$$\int \psi^{(t)}(s, x) d\xi = \int_0^t \phi(x) \xi(ds, dx)$$

$$\mathbb{E} \left[\left(\int \psi^{(t)}(s, x) d\xi \right)^2 \right] = \int \psi^{(t)}(s, x)^2 ds dx = t \int_{\mathbb{R}} \phi^2(x) dx$$

$\downarrow$
 BM with variance $t \int \phi^2 dx$.

EXAMPLE 3: $\mathbb{R}_+^n = \{t \in \mathbb{R}^n \mid t_i \geq 0; 1 \leq i \leq n\}$.

$$t \in \mathbb{R}_+^n. \quad W_t = W_{(t_1, \dots, t_n)} = \xi \left(\prod_{i=1}^n [0, t_i] \right)$$

$$\mathbb{E} W_t = 0 \quad \mathbb{E} W_t W_s = \prod_{i=1}^n [0, t_i \wedge s_i] = \prod_{i=1}^n (t_i \wedge s_i)$$

Brownian sheet.

Fix $a \geq 0$; $n=2$. $\{W_{a,t}\}_{t \geq 0}$ - BM with variance at .

$$\uparrow \quad \swarrow \quad \text{st=1 curve.} \quad X_t = W_{et, e^{-t}} \quad , \quad t \in \mathbb{R}.$$

$$\mathbb{E} X_t = 0, \quad \mathbb{E} [X_t^2] = e^t \cdot e^{-t} = 1.$$

$$\mathbb{E} [X_r X_u] = e^{-|r-u|} \Rightarrow X_t \text{ - O-U process.}$$

Along $s=t$, $M_t = W_{t,t} \stackrel{d}{=} N(0, t^2)$; Martingale.

Scaling: $\frac{1}{\alpha\beta} W_{\alpha^2 s, \beta^2 t} \stackrel{d}{=} W_{s,t}$

Inversion: $s, t \sim W_{1/s, 1/t} \stackrel{d}{=} W_{s,t}$

Translation: $W_{a+s, b+t} - W_{a+s, t} - W_{s, b+t} + W_{a,b} \stackrel{d}{=} W_{s,t}$
Brownian sheet.

(Walsh: Ch-1) - Markov property & continuity & LL & stopping points.

Application: (stochastic wave equation)

$$\frac{\partial^2 v}{\partial t^2} = \frac{\partial^2 v}{\partial x^2}; \quad v(0, x) = \frac{\partial v}{\partial t}(0, x) = 0. \quad x \in \mathbb{R}, \quad t \geq 0.$$

Forcing $\frac{\partial^2 v}{\partial t^2} = \frac{\partial^2 v}{\partial x^2} + f(t, x)$: Solⁿ $v(t, x) = \frac{1}{2} \int_0^t \int_{x+s-t}^{x+t-s} f(s, y) dy ds$

Verify directly by differentiating.

Rotate by $45^\circ \Rightarrow u = \frac{s-y}{\sqrt{2}}, \quad v = \frac{s+y}{\sqrt{2}} \quad \hat{v}(u, v) = v(s, y).$

$\hat{f}(u, v) = f(s, y) \quad \hat{v}(u, v) = \frac{1}{2} \int_0^v \int_{-u}^u \hat{f}(\alpha, \beta) d\alpha d\beta$

STOCHASTIC WAVE EQN: $x \in \mathbb{R}, \quad t \geq 0.$

$$\frac{\partial^2 w}{\partial t^2} = \frac{\partial^2 w}{\partial x^2} + \xi(dt, dx); \quad v(0, x) = \frac{\partial v}{\partial t}(0, x) = 0. \quad - (**)$$

$D = \{(u, v) \mid u \neq v \geq 0\} \quad R_{u,v} = D \cap (-\infty, u] \times (-\infty, v]$



$\hat{w}_{u,v} = \int_0^1 \int_0^1 \hat{w}(u, v)$

$\hat{w}_{u,v}$ is not a Brownian sheet (0 on $u+v=0$)

$\hat{w}_{u,v} - \hat{w}_{u,0} - \hat{w}_{0,v} \stackrel{d}{=} \tilde{w}_{u,v}$ (Brownian sheet $u, v \geq 0$).

Solution to (**): $v(t, x) = \frac{1}{2} \int_0^t \int_{x+s-t}^{x+t-s} \xi(dy, ds)$

$$\hat{V}(u, v) = \frac{1}{2} \int_0^v \int_0^u \tilde{\gamma}(d\alpha, d\beta) = \frac{1}{2} \tilde{\gamma}(R_{u,v}) = \frac{1}{2} \hat{W}_{u,v}.$$