

$\mathbb{Q}_{n \times n}$

Range ( $\mathbb{Q}$ ) = Column space of  $\mathbb{Q}$ .

$$= \{ b_{n \times 1} \mid \exists x_{n \times 1} : \mathbb{Q}x = b \}$$

$\mathbb{Q}_{*j}$  -  $j^{\text{th}}$  column of  $\mathbb{Q}$

$$= \{ b_{n \times 1} \mid x_1 \mathbb{Q}_{*1} + x_2 \mathbb{Q}_{*2} + \dots + x_n \mathbb{Q}_{*n} = b \}$$

$$= \text{Span} \{ \mathbb{Q}_{*1}, \mathbb{Q}_{*2}, \dots, \mathbb{Q}_{*n} \}$$

$$[\mathbb{Q} : b] \xrightarrow{\text{Row operations}} [\tilde{U} : \tilde{b}]$$

Reduced Echelon form.

• Step 1:- If  $x_{n \times 1} : \mathbb{Q}x = b \Rightarrow \tilde{U}x = \tilde{b}$

Step 2:- "1" stairs column's will form a basis for Column space  $\mathbb{Q}$

$$[\tilde{U} : \tilde{b}] = \begin{bmatrix} 1 & x & x & 0 & x & x & x & 0 & 1 & 0 & x & x \\ 0 & 1 & x & x & x & 0 & 0 & 1 & 0 & x & x & x \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

1      4      8      9

$\{ \mathbb{Q}_{*1}, \mathbb{Q}_{*4}, \mathbb{Q}_{*8}, \mathbb{Q}_{*9} \}$  are

basis for Column space of  $\mathbb{Q}$ .

- Basis of Column space of  $\mathbb{Q}$  form the columns of  $\mathbb{Q}$ .

1(a)

$$Q_{x1} = v_1 = \begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \end{pmatrix}$$

basis for  $\mathcal{B}(Q)$

$$Q_{x2} = v_2 = \begin{pmatrix} 1 \\ 2 \\ 1 \\ 1 \end{pmatrix}$$

$$Q_{x4} = v_4 = \begin{pmatrix} -2 \\ 1 \\ -2 \\ -2 \end{pmatrix}$$

$$\bullet \langle v_1, v_2 \rangle = 1 + 0 - 2 + 1 = 0$$

$v_1$  &  $v_2$  are orthogonal

$$\bullet v_4 = \begin{pmatrix} -2 \\ 1 \\ 2 \\ -2 \end{pmatrix}$$

$$\langle v_2, v_4 \rangle = -2 + 2 + 2 - 2 = 0$$

$$\langle v_1, v_4 \rangle = -2 + 0 + 4 - 2 = 0$$

$\{v_1, v_2, v_4\}$  orthogonal basis

$v_1, v_2$  $v_1 \neq 0, v_2 \neq 0$  $v_1 \neq \alpha v_2$  for some  $\alpha$ 

$$\text{Set } p = \frac{\langle v_2, v_1 \rangle}{\langle v_1, v_1 \rangle} \cdot v_1$$

$$\tilde{v}_2 = v_2 - p$$

$$\begin{aligned} \Rightarrow \langle \tilde{v}_2, v_1 \rangle &= \langle v_2, v_1 \rangle - \langle p, v_1 \rangle \\ &= \langle v_2, v_1 \rangle - \frac{\langle v_2, v_1 \rangle \langle v_1, v_1 \rangle}{\langle v_1, v_1 \rangle} \\ &= 0 \end{aligned}$$

$\{\tilde{v}_2, v_1\}$  are orthogonal



- projection of  $v_2$  onto  $v_1$

$$\cdot \quad \langle a, b \rangle = |a| |b| \cos(\theta)$$

- early 12<sup>th</sup> class

General:- If  $v_1, v_2, \dots, v_k$  are orthogonal  
 i.e.  $\langle v_i, v_j \rangle = 0$  and  $v_i \neq 0$   
 $i \neq j$   
 in some vector space  $V$

$x \in V$  &  $x \notin \text{Span}\{v_1, v_2, \dots, v_k\}$

Set  $p = \sum_{i=1}^k \frac{\langle x, v_i \rangle}{\langle v_i, v_i \rangle} v_i$

$$v_{k+1} = x - p$$

$\Rightarrow \{v_1, \dots, v_{k+1}\}$  are orthogonal.

Q1 @: Step 1  $[Q: \theta]$  - reduced one -  $[\tilde{Q}: \theta]$

If  $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_6 \end{bmatrix}$  &  $Qx = 0$

Then  $\tilde{Q}x = 0$

① -  $x_1 + 3x_3 - x_4 - x_6 = 0$

② -  $7x_2 - 7x_3 - x_4 - 8x_5 + 13x_6 = 0$

③ -  $x_4 + x_5 + x_6 = 0$

Pseudo code?  
 going forward

step 2 :-

$$(3) \Rightarrow x_4 = -x_5 - x_6 \quad - (4)$$

$$\begin{aligned} (2) \Rightarrow x_3 &= x_2 - \frac{x_4 + 8x_5 - 13x_6}{7} \\ &= x_2 - \frac{7x_5 - 14x_6}{7} \\ &= x_2 - x_5 + 2x_6 \quad - (5) \end{aligned}$$

$$\begin{aligned} (3) \quad x_1 &= -3x_3 + x_4 + x_6 \\ &= -3x_2 + 3x_5 - 6x_6 \\ &\quad - x_5 - x_6 + x_6 \\ &= -3x_2 + 2x_5 - 6x_6 \quad - (6) \end{aligned}$$

$$x_{n \times 1} : Qx = 0 \Rightarrow$$

$$x = \begin{bmatrix} -3x_2 + 2x_5 - 6x_6 \\ x_2 \\ x_2 - x_5 + 2x_6 \\ -x_5 - x_6 \\ x_5 \\ x_6 \end{bmatrix}$$

$$x_2, x_5, x_6 \in \mathbb{R}$$

$$= x_1 \begin{bmatrix} -3 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 0 \\ -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -6 \\ 0 \\ 2 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\{x : Qx = 0\} \quad \begin{matrix} v_1 \\ ||| \\ \end{matrix} \quad \begin{matrix} v_2 \\ ||| \\ \end{matrix} \quad \begin{matrix} v_3 \\ ||| \\ \end{matrix}$$

$$= \text{Span} \left\{ \begin{bmatrix} -3 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ -1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -6 \\ 0 \\ 2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

verify Independence ✓

$\Rightarrow \{v_1, v_2, v_3\}$  are a basis for  $\text{Null}(Q)$ .

Exercise: Given  $Q_{m \times n}$ :

write an

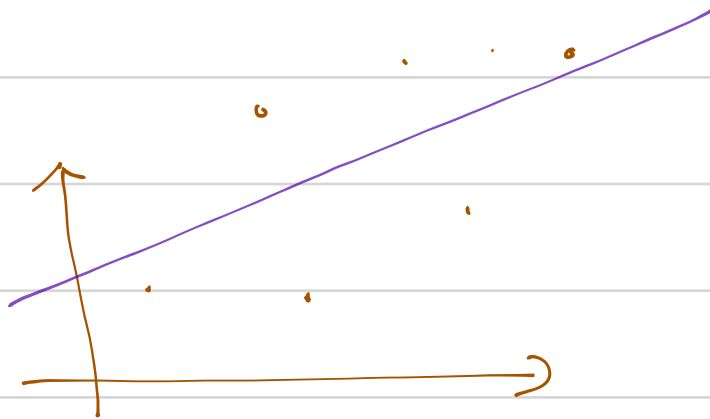
(a) R-code that will display a basis for Column space of  $Q$  from the columns of  $Q$  ... orthogonal basis

(b) R-code - for basis of  $\text{Null}(Q)$ .

# least-squares Method

$$x_1 \dots x_n$$

$$y_1 \dots y_n$$



$$y = \alpha + \beta x$$

Solve for  $\alpha, \beta$ :

$$\begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

• System is inconsistent

$$A = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \quad c = \begin{bmatrix} \alpha \\ \beta \end{bmatrix} \quad y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$\arg \min_c \|y - Ac\|_2^2 = \arg \min_{\alpha, \beta} \sum_{i=1}^n (y_i - \alpha - \beta x_i)^2$$

↙

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(c) = \|y - Ac\|_2^2$$

$$= (y - Ac)^T (y - Ac)$$

$$= y^T y - y^T A c - c^T A^T y + c^T A^T A c$$

• Set  $\nabla f(c) = 0$  critical points

• Orthogonal projections idea

— Exercise  $\Rightarrow -2A^T y + 2A^T A c = 0$

$$\Rightarrow c \text{ solves :- } \boxed{A^T A c = A^T y} \equiv \text{Normal Equations}$$