

Perturbation bounds for Mostow's decomposition

Priyanka Grover

Shiv Nadar University

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Mostow's decomposition

Polar decomposition

Any invertible matrix A can be written uniquely as $A = UP$, U unitary, P positive definite

Mostow's decomposition

Every invertible matrix Z can be uniquely factorized as

$$Z = W e^{iK} e^S,$$

where W is a unitary matrix, S is a real symmetric matrix and K is a real skew symmetric matrix.

$$e^{iK} = P_1, e^S = P_2$$

P_1, P_2 are positive definite

Moreover, P_1 is circular (i.e. $\overline{P_1} P_1 = I$)

So

$$Z = W P_1 P_2$$

Perturbation bounds

\mathcal{X}, \mathcal{Y} : normed spaces (or their open subsets) or Lie groups

$$f: \mathcal{X} \rightarrow \mathcal{Y}$$

$$\|f(u) - f(v)\| \leq C\|u - v\|$$

$$Z = W P_1 P_2$$

$$Z \mapsto W, \quad Z \mapsto P_1, \quad Z \mapsto P_2$$

If f is differentiable at $u \in \mathcal{X}$, then for every $v \in \mathcal{X}$ ($v \in \text{Lie Algebra}$)

$$Df(u)(v) = \left. \frac{d}{dt} \right|_{t=0} f(u + tv).$$

$$\left(Df(u)(uv) = \left. \frac{d}{dt} \right|_{t=0} f(ue^{tv}). \right)$$

Mean value theorem

Let $f : \mathcal{X} \rightarrow \mathcal{Y}$ be a differentiable map. Let $u, v \in \mathcal{X}$ and let L be the line segment joining them. Then

$$\|f(u) - f(v)\| \leq \|u - v\| \sup_{w \in L} \|Df(w)\|.$$

Taylor's theorem

Let $f : \mathcal{X} \rightarrow \mathcal{Y}$ be a $(p + 1)$ -times differentiable map. For $u \in \mathcal{X}$ and for small h ,

$$\left\| f(u + h) - f(u) - \sum_{k=1}^p \frac{1}{k!} D^k f(u)(h, \dots, h) \right\| = O(\|h\|^{p+1}).$$

From here, first order perturbation bounds can be found.

$$\|f(u + h) - f(u)\| \leq \|Df(u)\| \|h\| + O(\|h\|^2).$$

Notations

$M(n, \mathbb{C})$: space of $n \times n$ complex matrices

$GL(n, \mathbb{C})$: set of invertible matrices

$P(n, \mathbb{C})$: set of $n \times n$ positive definite matrices.

$H(n, \mathbb{C})$: space of $n \times n$ Hermitian matrices

$SH(n, \mathbb{C})$: space of $n \times n$ skew-Hermitian matrices

$U(n, \mathbb{C})$: set of $n \times n$ unitary matrices.

Notations

- $\|A\|$: operator norm of A
If $s_1 \geq s_2 \geq \dots \geq s_n \geq 0$ are singular values of A , then $\|A\| = s_1$.

- $\|A\|$: unitarily invariant norm of A

$$\|A\| = \|UAV\| \text{ for all } U, V \text{ unitary}$$

- \bar{A} : complex conjugate of A



$$\|A\| = \|A^*\| = \|\bar{A}\|$$



$$\|ABC\| \leq \|A\| \|B\| \|C\|$$

- Let \mathcal{W} be a subspace of $(\mathbb{M}(n, \mathbb{C}), \|\cdot\|)$ and let $\mathcal{T} : \mathcal{W} \rightarrow \mathbb{M}(n, \mathbb{C})$ be a linear map. Then

$$\|\mathcal{T}\| = \sup\{\|\mathcal{T}(X)\| : \|X\| = 1\}.$$

Matrix Factorization

- $\mathbb{A}, \mathbb{A}_1, \mathbb{A}_2$: classes of matrices (open subsets of $\mathbb{M}(n, \mathbb{C})$ or Lie groups)
- Every $A \in \mathbb{A}$ has a unique factorization

$$A = A_1 A_2$$

- The decomposition gives a map $\varrho : \mathbb{A} \rightarrow \mathbb{A}_1 \times \mathbb{A}_2$

$$\varrho(A) = (\varrho_1(A), \varrho_2(A)) = (A_1, A_2)$$

- To study variation of A_1, A_2 with A , it is natural to study the derivatives $D\varrho_1(A), D\varrho_2(A)$.
- The maps ϱ_1, ϱ_2 are complicated to describe.

- Instead, consider the inverse map

$$\tau : \mathbb{A}_1 \times \mathbb{A}_2 \rightarrow \mathbb{A}$$

defined as

$$\tau(A_1, A_2) = A_1 A_2 = A$$

- τ is a product map so computing the derivative is easy.
- **Inverse function theorem:** Let \mathbb{A} be an open subset of \mathbb{R}^n and let $f : \mathbb{A} \rightarrow \mathbb{R}^n$ be a continuously differentiable map. Let $p \in \mathbb{A}$ such that $\det Df(p) \neq 0$. Then there is an open set U containing p and an open set V containing $f(p)$ such that $f : U \rightarrow V$ has a differentiable inverse $f^{-1} : V \rightarrow U$ and for $y \in V$,

$$D(f^{-1})(y) = [Df(f^{-1}(y))]^{-1}.$$

Inverse Function Theorem

Let $f : N \rightarrow M$ be a continuously differentiable map between two manifolds of the same dimension, and $p \in N$. Suppose for some charts (U, ϕ) around $p \in N$ and (V, ψ) around $f(p)$ in M , $f(U) \subset V$. Then f is locally invertible at p if the Jacobian determinant is nonzero.



$$\tau : \mathbb{A}_1 \times \mathbb{A}_2 \rightarrow \mathbb{A}$$

$$D\tau(A_1, A_2) : T_{A_1}\mathbb{A}_1 + T_{A_2}\mathbb{A}_2 \rightarrow T_A\mathbb{A},$$

where $T_A\mathbb{A}$ is the tangent space to \mathbb{A} at the point A

- When \mathbb{A} is an open set, then $T_A\mathbb{A} = \mathbb{M}(n, \mathbb{C})$ for every $A \in \mathbb{A}$. All tangential vectors at A are of the form $A + tB$, $B \in \mathbb{M}(n, \mathbb{C})$.
- When \mathbb{A} is a Lie group, then $T_I\mathbb{A}$ is the Lie algebra corresponding to this Lie group. The tangent space at any other point is $A \cdot T_I\mathbb{A}$. The tangent vectors at A are written as Ae^{tB} , where B is from the Lie algebra.

Polar decomposition

$A \in \mathrm{GL}(n, \mathbb{C})$ can be written uniquely as $A = UP$, U unitary, P positive definite

$$\varrho_1 : \mathrm{GL}(n, \mathbb{C}) \rightarrow \mathrm{U}(n, \mathbb{C})$$

$$\varrho_2 : \mathrm{GL}(n, \mathbb{C}) \rightarrow \mathbb{P}(n, \mathbb{C})$$

$$T_A \mathrm{GL}(n, \mathbb{C}) = \mathrm{M}(n, \mathbb{C}), T_U \mathrm{U}(n, \mathbb{C}) = U \mathrm{SH}(n, \mathbb{C}), T_P \mathbb{P}(n, \mathbb{C}) = \mathbb{H}(n, \mathbb{C})$$

For $S \in \mathrm{SH}(n, \mathbb{C})$, $H \in \mathbb{H}(n, \mathbb{C})$,

$$\begin{aligned} D_{\tau}(U, P)(US, H) &= \left. \frac{d}{dt} \right|_{t=0} \tau(Ue^{tS}, P + tH) \\ &= \left. \frac{d}{dt} \right|_{t=0} Ue^{tS}(P + tH) \\ &= USP + UH. \end{aligned}$$

Polar decomposition

For all $X \in \mathbb{M}(n, \mathbb{C})$, we want to find $D_{\varrho}(A)(X)$.

Suppose

$$D_{\varrho}(A)(UX) = (US, H) \text{ for some } S \in \mathbb{SH}(n, \mathbb{C}), H \in \mathbb{H}(n, \mathbb{C})$$

$$UX = D_{\tau}(U, P)(US, H) = USP + UH$$

$$X = SP + H$$

In this case, S and H can be found explicitly. But even if they can't be found, this gives adequate information to get bounds on $D_{\varrho_1}(A)$ and $D_{\varrho_2}(A)$.

Tangent spaces at U and P give

$$\mathbb{M}(n, \mathbb{C}) = \mathbb{H}(n, \mathbb{C}) + \mathbb{SH}(n, \mathbb{C}).$$

If \mathcal{P}_1 and \mathcal{P}_2 are the corresponding projection operators , then

$$\mathcal{P}_1(A) = \frac{A - A^*}{2}$$

$$\mathcal{P}_2(A) = \frac{A + A^*}{2}$$

So

$$\|\mathcal{P}_1\| = \|\mathcal{P}_2\| = 1.$$

Finding S and H

$$X = SP + H, X \in \mathbb{M}(n, \mathbb{C}), S \in \mathbb{SH}(n, \mathbb{C}), H \in \mathbb{H}(n, \mathbb{C})$$

$$X^* = -PS + H$$

Subtract

$$X - X^* = SP + PS$$

This is a special case of well known **Sylvester's equation**.

Sylvester equation

$$AX - XB = Y$$

If $\sigma(A)$ and $\sigma(B)$ are spectra of A and B such that $\sigma(A) \cap \sigma(B) = \phi$, then Sylvester's equation has a unique solution X for every Y .

If $\sigma(A)$ is contained in the open right half-plane and $\sigma(B)$ is contained in the open left half-plane, then

$$X = \int_0^{\infty} e^{-tA} Y e^{tB} dt.$$

(Note: If $a - b \neq 0$, then $ax - xb = y$ has a unique solution $x = \frac{y}{a-b}$. If $\operatorname{Re}(b - a) < 0$, then $\int_0^{\infty} e^{t(b-a)} dt$ is convergent and has the value $\frac{1}{a-b}$. In this case, the solution of $ax - xb = y$ can be expressed as $x = \int_0^{\infty} e^{t(b-a)} y dt$.)

Bound on $D_{\rho_1}(A)$

$$2i \operatorname{Im} X = X - X^* = SP + PS$$

$$S = 2i \int_0^{\infty} e^{-tP} \operatorname{Im} X e^{-tP} dt$$

Thus

$$\|S\| \leq 2 \left(\int_0^{\infty} \|e^{-tP}\|^2 dt \right) \|\operatorname{Im} X\|$$

Easy to compute

$$\int_0^{\infty} \|e^{-tP}\|^2 dt = \frac{\|P^{-1}\|}{2} = \frac{\|A^{-1}\|}{2}$$

$$\|S\| \leq \|A^{-1}\| \|\operatorname{Im} X\| \leq \|A^{-1}\| \|X\|$$

Hence

$$\|D_{\rho_1}(A)(UX)\| \leq \|A^{-1}\| \|X\|$$

For $X = iI/\|I\|$, this is an equality.

Bound on $D_{\ell_2}(A)$

$$X = SP + H$$

$$\begin{aligned}\|H\| &\leq \|X\| + \|SP\| \\ &\leq \|X\| + \|S\| \|P\| \\ &\leq \|X\| + \|A^{-1}\| \|X\| \|P\| \\ &= [1 + \text{cond}(A)] \|X\|,\end{aligned}$$

where $\text{cond}(A) = \|A\| \|A^{-1}\|$.

So

$$\|D_{\ell_2}(A)\| \leq 1 + \text{cond}(A).$$

Perturbation bounds

First order perturbation bounds can be found using Taylor's theorem.

Let \tilde{A} represent a perturbation of A (\tilde{A} is in a neighbourhood of A). Let $\tilde{A} = \tilde{U}\tilde{P}$. Then Taylor's theorem gives

$$\|\tilde{U} - U\| \leq \|A^{-1}\| \|\tilde{A} - A\| + O(\|\tilde{A} - A\|^2).$$

This is usually represented as

$$\|\tilde{U} - U\| \lesssim \|A^{-1}\| \|\tilde{A} - A\|.$$

Similarly,

$$\|\tilde{P} - P\| \lesssim [1 + \text{cond}(A)] \|\tilde{A} - A\|.$$

Mostow's decomposition

$$Z = W P_1 P_2$$

Recently, Bhatia (2013) gave another proof of Mostow's decomposition theorem, giving explicitly what these factors are.

Related to geometric mean of two positive definite matrices.

Geometric mean

For $A, B \in \mathbb{P}(n, \mathbb{C})$ their geometric mean is defined as

$$A\#B = A^{1/2} \left(A^{-1/2} B A^{-1/2} \right)^{1/2} A^{1/2}$$

- It is the unique positive solution of the *Riccati equation*

$$XA^{-1}X = B$$



$$A\#B = \max \left\{ X : X = X^*, \begin{bmatrix} A & X \\ X & B \end{bmatrix} \geq O \right\}$$



$$A\#B = A(A^{-1}B)^{1/2} = (AB^{-1})^{1/2}B,$$

where $(A^{-1}B)^{1/2}$ and $(AB^{-1})^{1/2}$ are the unique square roots of $A^{-1}B$ and AB^{-1} , respectively, with positive eigenvalues.

Mostow's decomposition

$$A = Z^*Z$$

$A\#\bar{A}$ is positive definite

$$(A\#\bar{A})^{1/2} = P_2 = e^S, S \text{ real symmetric}$$

$$P_1 = (e^{-S}Ae^{-S})^{1/2}$$

P_1 is positive definite and circular

$$P_1 = e^{iK}, K \text{ real skew symmetric}$$

$$W = Ze^{-S}e^{-iK}$$

Then W is unitary

Derivative of geometric mean (–, Mishra (2017))

Let $G : \mathbb{P}(n, \mathbb{C}) \times \mathbb{P}(n, \mathbb{C}) \rightarrow \mathbb{P}(n, \mathbb{C})$ be the map defined as

$$G(A, B) = A\#B = A^{1/2} \left(A^{-1/2} B A^{-1/2} \right)^{1/2} A^{1/2}.$$

Since $A \mapsto A^{1/2}$ is a differentiable function on $\mathbb{P}(n, \mathbb{C})$, G is a differentiable map.

$$DG(A, B)(X, Y) = \left. \frac{d}{dt} \right|_{t=0} G(A+tX, B+tY) \text{ for all } X, Y \in \mathbb{H}(n, \mathbb{C}).$$

Derivative of geometric mean

$$X, Y \in \mathbb{H}(n, \mathbb{C})$$

For sufficiently small t

$$G(A + tX, B + tY)(A + tX)^{-1}G(A + tX, B + tY) = B + tY.$$

Differentiating with respect to t at 0, we get

$$\begin{aligned} (DG(A, B)(X, Y))A^{-1}G(A, B) - G(A, B)(A^{-1}XA^{-1})G(A, B) \\ + G(A, B)A^{-1}(DG(A, B)(X, Y)) = Y. \end{aligned}$$

(using $DA^{-1}(X) = -A^{-1}XA^{-1}$)

Put $D = DG(A, B)(X, Y)$ and $C = A^{-1}G(A, B) = (A^{-1}B)^{1/2}$.

$$C^*D + DC = Y + C^*XC.$$

Derivative of geometric mean

For $X, Y \in \mathbb{H}(n, \mathbb{C})$

$$\begin{aligned} DG(A, B)(X, Y) &= \int_0^\infty e^{-tC^*} (Y + C^*XC) e^{-tC} dt \\ &= \int_0^\infty e^{-t(BA^{-1})^{1/2}} (Y + (BA^{-1})^{1/2}X(A^{-1}B)^{1/2}) e^{-t(A^{-1}B)^{1/2}} dt \end{aligned}$$

$$\begin{aligned} |||DG(A, B)||| &= \sup\{|||DG(A, B)(X, Y)||| : |||(X, Y)||| = 1\}, \\ &\quad \text{where } |||(X, Y)||| = \max\{|||X|||, |||Y|||\} \\ &\leq \left(\int_0^\infty \|e^{-t(A^{-1}B)^{1/2}}\|^2 dt \right) \left(1 + \|(A^{-1}B)^{1/2}\|^2 \right). \end{aligned}$$

Mostow's decomposition

$$Z = WP_1P_2$$

$$\varrho_2 : Z \mapsto P_2:$$

$$P_2 = (Z^*Z\#\overline{Z^*Z})^{1/2}$$

Then

$$\varrho_2 = f \circ G \circ g \circ h,$$

where $f : t \mapsto t^{1/2}$, $g : A \mapsto (A, \overline{A})$, $h : Z \mapsto Z^*Z$.

Chain rule:

$$D\varrho_2(Z) = Df(Z^*Z\#\overline{Z^*Z}) \circ DG(Z^*Z, \overline{Z^*Z}) \circ Dg(Z^*Z) \circ Dh(Z)$$



$$\|Df(A)\| \leq \frac{1}{2}\|A^{-1}\|^{1/2}$$

- $\|A\#B\| \leq \|A\|^{1/2}\|B\|^{1/2}$

Bound for $\|D_{\varrho_2}(Z)\|$

$$\|D_{\varrho_2}(Z)(A)\| \leq \frac{1}{2} \|Z^{-1}\| \|DG(Z^*Z, \overline{Z^*Z})(Z^*A + AZ, \overline{Z^*A + AZ})\|$$

Let $C = (Z^*Z)^{-1} (Z^*Z \# \overline{Z^*Z}) = ((Z^*Z)^{-1} \overline{Z^*Z})^{1/2}$. Then $\|C\| \leq \text{cond}(Z)^2$.

$$\|D_{\varrho_2}(Z)(A)\| \leq \frac{1}{2} \|Z^{-1}\| \beta(Z) (1 + \|C\|^2) \|Z^*A + AZ\|,$$

where $\beta(Z) = \int_0^\infty \|e^{-t((Z^*Z)^{-1} \overline{Z^*Z})^{1/2}}\|^2 dt$

$$\|D_{\varrho_2}(Z)(A)\| \leq \beta(Z) \text{cond}(Z) (1 + \text{cond}(Z)^4) \|A\|$$

Mostow's decomposition

$\varrho_1 : Z \mapsto P_1, \varrho_0 : Z \mapsto W:$

\mathbb{P}_{circ} : the set of circular positive definite matrices.

$$P_1 \in \mathbb{P}_{\text{circ}}$$

$$\varrho(Z) = (\varrho_0(Z), \varrho_1(Z), \varrho_2(Z))$$

We are interested in $D_{\varrho_1}(Z)$ and $D_{\varrho_0}(Z)$.

Tangent spaces?

At W , it is $W \text{SH}(n, \mathbb{C})$.

At P_1 ?

Tangent space at I

Consider any smooth curve $\gamma(t)$ in \mathbb{P}_{circ} , with $\gamma(0) = I$. We have

$$\overline{\gamma(t)}\gamma(t) = I$$

and

$$\gamma(t)^* = \gamma(t).$$

Differentiating at $t = 0$ gives that $\overline{\gamma'(0)} + \gamma'(0) = 0$ so that

$\gamma'(0)$ is a purely imaginary matrix.

Also, $\gamma'(0)$ is Hermitian.

So

$$T_I\mathbb{P}_{circ} = i\mathbb{SH}(n, \mathbb{R}),$$

where $\mathbb{SH}(n, \mathbb{R})$: space of $n \times n$ real skew symmetric matrices.

Tangent space at P_1

To calculate $T_{P_1}\mathbb{P}_{circ}$, consider $\gamma(t)$ in \mathbb{P}_{circ} , with $\gamma(0) = P_1$. So

$$\overline{\gamma'(0)}P_1 + \overline{P_1}\gamma'(0) = 0.$$

For every $J \in \mathbb{SH}(n, \mathbb{R})$, the matrix $P_1^{1/2}iJP_1^{1/2}$ satisfies the above equation. A count on dimensions shows that the tangent space at any point P_1 is given by $iP_1^{1/2}\mathbb{SH}(n, \mathbb{R})P_1^{1/2}$.

$$D_{\varrho}(Z) : \mathbb{M}(n, \mathbb{C}) \rightarrow W \text{SH}(n, \mathbb{C}) \oplus i P_1^{1/2} \text{SH}(n, \mathbb{R}) P_1^{1/2} \oplus \mathbb{H}(n, \mathbb{R})$$

Suppose

$$D_{\varrho}(Z)(A) = (WX_0, i P_1^{1/2} Y_1 P_1^{1/2}, Y_2),$$

where $X_0 \in \text{SH}(n, \mathbb{C})$, $Y_1 \in \text{SH}(n, \mathbb{R})$ and $Y_2 \in \mathbb{H}(n, \mathbb{R})$.

$$D_{\varrho}(Z)(A) = (WX_0, iP_1^{1/2}Y_1P_1^{1/2}, Y_2),$$

$$D_{\tau}(W, P_1, P_2)(WX_0, iP_1^{1/2}Y_1P_1^{1/2}, Y_2) = A.$$

By definition,

$$\begin{aligned} & D_{\tau}(W, P_1, P_2)(WX_0, iP_1^{1/2}Y_1P_1^{1/2}, Y_2) \\ &= \left. \frac{d}{dt} \right|_{t=0} \tau(We^{tX_0}, P_1^{1/2}e^{itY_1}P_1^{1/2}, P_2 + tY_2) \\ &= \left. \frac{d}{dt} \right|_{t=0} We^{tX_0}P_1^{1/2}e^{itY_1}P_1^{1/2}(P_2 + tY_2) \\ &= WX_0P_1P_2 + WP_1^{1/2}(iY_1)P_1^{1/2}P_2 + WP_1Y_2. \end{aligned}$$

$$WX_0P_1P_2 + WP_1^{1/2}(iY_1)P_1^{1/2}P_2 + WP_1Y_2 = A,$$

where

$$X_0^* = -X_0, \quad \overline{Y_1} = Y_1, \quad Y_1^t = -Y_1, \quad \overline{Y_2} = Y_2, \quad Y_2^t = Y_2$$

i.e.

$$X_0 + P_1^{1/2}(iY_1)P_1^{-1/2} = (W^*A - P_1Y_2)(P_1P_2)^{-1}$$

Taking adjoint,

$$-X_0 + P_1^{-1/2}(iY_1)P_1^{1/2} = (P_1P_2)^{-1}(A^*W - Y_2P_1)$$

Add.

$$\begin{aligned} & (P_1^{1/2}(iY_1)P_1^{1/2})P_1^{-1} + P_1^{-1}(P_1^{1/2}(iY_1)P_1^{1/2}) \\ & = \operatorname{Re} \left((W^*A - P_1Y_2)(P_1P_2)^{-1} \right). \end{aligned}$$

$$P_1^{1/2}(iY_1)P_1^{1/2} = \int_0^\infty e^{-tP_1^{-1}} \operatorname{Re} \left((W^*A - P_1Y_2)(P_1P_2)^{-1} \right) e^{-tP_1^{-1}} dt.$$

We get

$$\begin{aligned} |||D_{\varrho_1}(Z)(A)||| &= |||P_1^{1/2}(iY_1)P_1^{1/2}||| \\ &\leq \left(\int_0^\infty \|e^{-tP_1^{-1}}\|^2 dt \right) |||\operatorname{Re} \left((W^*A - P_1Y_2)(P_1P_2)^{-1} \right)||| \\ &\leq \frac{\|P_1\|}{2} |||(W^*A - P_1Y_2)(P_1P_2)^{-1}||| \\ &\leq \frac{\operatorname{cond}(P_1) \|P_2^{-1}\|}{2} (1 + \|P_1\| \|Y_2\|) |||A|||. \end{aligned}$$

Similarly, we obtain

$$X_0 P_1 + P_1 X_0 = 2i \operatorname{Im} \left((W^* A - P_1 Y_2) P_2^{-1} \right),$$

which gives

$$\begin{aligned} D_{\varrho_0}(Z)(A) &= X_0 \\ &= \int_0^\infty e^{-tP_1} \operatorname{Im} \left((W^* A - P_1 Y_2) P_2^{-1} \right) e^{-tP_1} dt. \end{aligned}$$

So

$$\begin{aligned} |||D_{\varrho_0}(Z)(A)||| &= |||X_0||| \\ &\leq \left(\int_0^\infty \|e^{-tP_1}\|^2 dt \right) |||(W^* A - P_1 Y_2) P_2^{-1}||| \\ &\leq \frac{\|P_1^{-1}\| \|P_2^{-1}\|}{2} (1 + \|P_1\| \|Y_2\|) |||A|||. \end{aligned}$$

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THANK YOU!