Role of Birkhoff-James orthogonality in the study of geometric properties of operator spaces

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* This is a joint work with Dr. D. Sain, Dr. P. Ghosh., A. Ray, and A. Mal

**This presentation is for OTOA-2018.

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• The geometric interpretation of a smooth point in a two dimensional real normed linear space goes like this



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 $T\bot_B(A_1+A_2).$

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Theorem. Let $T \in B(\mathbb{X}, \mathbb{Y})$ and $M_T = D \cup (-D)$, where D is a non-empty connected subset of $S_{\mathbb{X}}$. Then for any $A \in B(\mathbb{X}, \mathbb{Y})$, $T \perp_B A$ iff there exists $x \in M_T$ such that $Tx \perp_B Ax$.

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▶ **Remark.** In case X and Y are Hilbert spaces, *T* is smooth iff $M_T = \{\pm x_0\}$.

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Sufficiency: Let $T \perp_B A_1$ and $T \perp_B A_2$. Then $Tx_0 \perp_B A_1x_0$ and $Tx_0 \perp_B A_2x_0$. Thus $Tx_0 \perp_B (A_1 + A_2)x_0$ and so $T \perp_B (A_1 + A_2)$.

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Theorem. Let \mathbb{X} , \mathbb{Y} be normed linear spaces. Let $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $M_T = \{\pm x_0\}$. Further *T* satisfies the property : Given any $\delta > 0$, if $\{H_\alpha : \alpha \in \Lambda\}$ is the collection of all hyperspaces such that $d(x_0, H_\alpha) > \delta$ then $\sup\{\|Tx\| : x \in (\bigcup_\alpha H_\alpha) \cap S_{\mathbb{X}}\} < \|T\|$. Then for any $A \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$, $T \perp_B A$ if and only if $Tx_0 \perp_B Ax_0$.

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(i)For any $A \in B(\mathbb{X}, \mathbb{Y})$, $T \perp_B A \Leftrightarrow Tx_0 \perp_B Ax_0$ for some $x_0 \in M_T$ (ii) $M_T = D \cup (-D)$, where *D* is a non-empty connected subset of $S_{\mathbb{X}}$, span(D) is finite dimensional subspace of \mathbb{X} and $\|T\|_{span(D)^{\perp}} < \|T\|$.

However, assuming $M_T = \{\pm x_0\}$ we have the following results for orthogonality and smoothness.

Theorem. Let \mathbb{X} , \mathbb{Y} be normed linear spaces. Let $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $M_T = \{\pm x_0\}$. Further T satisfies the property : Given any $\delta > 0$, if $\{H_\alpha : \alpha \in \Lambda\}$ is the collection of all hyperspaces such that $d(x_0, H_\alpha) > \delta$ then $\sup\{\|Tx\| : x \in (\cup_\alpha H_\alpha) \cap S_{\mathbb{X}}\} < \|T\|$. Then for any $A \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$, $T \perp_B A$ if and only if $Tx_0 \perp_B Ax_0$. In addition, if Tx_0 is smooth, then T is also smooth.

This again gives a sufficient condition for the smoothness of an arbitrary bounded linear operator. For the necessary part we could obtain the following which is a little different from the sufficient part:

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Theorem. Let \mathbb{X} , \mathbb{Y} be normed linear spaces. Let $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $M_T \neq \emptyset$. Suppose that T is smooth. Then (i) $M_T = \{\pm x_0\}$, for some $x_0 \in S_{\mathbb{X}}$.

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Theorem. Let \mathbb{X} , \mathbb{Y} be normed linear spaces. Let $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $M_T \neq \emptyset$. Suppose that *T* is smooth. Then (i) $M_T = \{\pm x_0\}$, for some $x_0 \in S_{\mathbb{X}}$. (ii) Tx_0 is a smooth point.

This again gives a sufficient condition for the smoothness of an arbitrary bounded linear operator. For the necessary part we could obtain the following which is a little different from the sufficient part:

Theorem. Let \mathbb{X} , \mathbb{Y} be normed linear spaces. Let $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $M_T \neq \emptyset$. Suppose that T is smooth. Then (i) $M_T = \{\pm x_0\}$, for some $x_0 \in S_{\mathbb{X}}$. (ii) Tx_0 is a smooth point. (iii) $\sup\{\|Tx\| : x \in H_\alpha \cap S_{\mathbb{X}}\} < \|T\|$ for all $\alpha \in \Lambda$, where $\{H_{\alpha:\alpha \in \Lambda}\}$ is the collection of all hyperspaces such that $d(x_0, H_\alpha) > 0$.

• An element $x \in S_X$ is said to be an extreme point of B_X if for any $y, z \in B_X$ and $t \in (0, 1), x = (1 - t)y + tz$ implies that x = y = z.

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• An operator $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ is said to be an extreme contraction on $\mathbb{B}(\mathbb{X}, \mathbb{Y})$ if T is an extreme point of the unit ball of $\mathbb{B}(\mathbb{X}, \mathbb{Y})$, i.e., for any $T_1, T_2 \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $t \in (0, 1), T = (1 - t)T_1 + tT_2$ implies that $T = T_1 = T_2$.

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The following theorem explores the role of norm attainment set of an operator on characterizing extreme contraction on a Banach space.

• An element $x \in S_X$ is said to be an extreme point of B_X if for any $y, z \in B_X$ and $t \in (0, 1), x = (1 - t)y + tz$ implies that x = y = z.

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• An operator $T \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ is said to be an extreme contraction on $\mathbb{B}(\mathbb{X}, \mathbb{Y})$ if T is an extreme point of the unit ball of $\mathbb{B}(\mathbb{X}, \mathbb{Y})$, i.e., for any $T_1, T_2 \in \mathbb{B}(\mathbb{X}, \mathbb{Y})$ and $t \in (0, 1), T = (1 - t)T_1 + tT_2$ implies that $T = T_1 = T_2$.

The following theorem explores the role of norm attainment set of an operator on characterizing extreme contraction on a Banach space.

Theorem. Let \mathbb{X} be a finite-dimensional polygonal Banach space and let \mathbb{Y} be a strictly convex normed linear space. Then $T \in \mathbb{B}(X; Y)$ with ||T|| = 1 is an extreme contraction if and only if span $(M_T \cap E_{\mathbb{X}}) = \mathbb{X}$.

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Thank You