

Due Date: February 21st, 2007

Problems to be turned in: 1, 2(b)-(f)

- Starting with the code `GEshow` in the NMM toolbox develop a `GErectangular` function that performs Gaussian elimination *only* for a $m \times n$ matrix. The function should return \tilde{A} , the triangularised augmented matrix.

Bonus Question¹ : Write a general program in OCTAVE, `GEgeneral`, which solves a linear $m \times n$ system of equations.

- Centrifugal pumps are common devices used to move liquid through piping systems. The key question there is to determine the pressure head h of the pump given q the flow rate. Start with the model specified in `pumpcurve` code in the NMM toolbox.

- Consider q and h from the following table:

$q(m^3/s)$	0.0001	0.00025	0.0008	0.001	0.0014
$h(m)$	115	114.2	110	105.5	92.5

Using the first three data points, write down the equation you get between h and q .

- Modify the `pumpcurve` function to accept q and h vectors of arbitrary length as input. Using all data points (above) except the fourth, use your function to find the cubic polynomial interpolant. Also find the condition number of A . Let c be the coefficients of the polynomial.
- Replace the second point to 114 from 114.2. Do as in previous part to get \tilde{c} .
- Find the relative difference vector $d = \frac{\tilde{c}-c}{c}$ for all i .
- Plot h vs q , and find the largest difference in the value of h from 100 points between $\min(q)$ and $\max q$ in both the cases.
- Discuss the practical significance on the perturbation of h values on the coefficient c and the values of h obtained by the interpolation function.

- Let $A = \begin{bmatrix} 1 & 0 \\ 0 & \epsilon \end{bmatrix}$.

- Compute the condition number of A using the 1 norm or ∞ norm.
- Deduce that the matrix is ill-conditioned for small ϵ .
- Let $b = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ and $\delta b = \begin{bmatrix} 0 \\ \epsilon \end{bmatrix}$ Show that

$$\frac{\|\delta x\|}{\|x\|} = \kappa(A) \frac{\|\delta b\|}{\|b\|}$$

¹Eventual Prize: Carrot Cake at end of semester

At the end of this chapter you should be able to

1. Describe the most efficient procedures for solving $Lx = b$ or $Ux = b$ when L is lower triangular and U is upper triangular.
2. Name the solution algorithm most commonly used for solving $Ax = b$.
3. Write the equation that defines the residual vector.
4. Describe the significance of $\kappa(A)$ on the reliability of the numerical solution to $Ax = b$.
5. Describe the reason for pivoting. Is pivoting a remedy for ill-conditioned systems?
6. Estimate the number of correct significant digits in the numerical solution to $Ax = b$ given values of ϵ_m and $\kappa(A)$.
- 7.
8. State conditions required for a successful LU factorization of A . Write (describe) a procedure for solving $Ax = b$ given an LU factorization of A .
9. State conditions required for a successful Cholesky factorization of A . Write (describe) a procedure for solving $Ax = b$ given a Cholesky factorization of A .
10. Use OCTAVE and the LU factorization of A to solve several systems of equations that have the same A and a sequence of different b .
11. Use OCTAVE and a Cholesky factorization of A to solve several systems of equations that have the same A and a sequence of different b .
12. List the order of magnitude work estimates for Gaussian elimination with back substitution, LU factorization, and Cholesky factorization.

1. Using the code of the `lupiv` function in the NMM toolbox (directory `-linalg`) solve for x when $Ax = b$ when

$$A = \begin{bmatrix} 2 & 4 & -2 & -2 \\ 1 & 2 & 4 & -3 \\ -3 & -3 & 8 & -2 \\ -1 & 1 & 6 & -3 \end{bmatrix} \quad b = \begin{bmatrix} -4 \\ 5 \\ 7 \\ 7 \end{bmatrix}$$

Provide the commands used by you in your answer.

2. Using code of the `cholesky` function in the NMM toolbox (directory `-linalg`) solve for x when $Ax = b$ when

$$A = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix} \quad b = \begin{bmatrix} -1 \\ 0 \\ 0 \\ -2 \end{bmatrix}$$

Provide the commands used by you in your answer.